

# L<sup>A</sup>T<sub>E</sub>X sample document

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## Basic terms

### Number fields

- N Natural numbers
- Z Integer numbers
- R Real numbers
- C Complex numbers

### Vectors

A row vector  $\mathbf{x}$  and a column vector  $\mathbf{y}$ :

$$\mathbf{x} = (x_1, x_2, \dots, x_N) \qquad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix}.$$

The set of  $N$  dimensional real vectors is denoted  $\mathbb{R}^N$ , so  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^N$ . The  $i$ 'th element of  $\mathbf{x}$  is denoted  $[\mathbf{x}]_i$  or sometimes (like above) just  $x_i$ .

**MATLAB:** To define a row vector with elements 1, 2, 3, type `x=[1,2,3]`. To define a column vector with the same elements, type `y=[1;2;3]`.

### Matrices

An  $N \times M$  matrix:

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1M} \\ a_{21} & a_{22} & \dots & a_{2M} \\ \vdots & & \ddots & \vdots \\ a_{N1} & a_{N2} & \dots & a_{NM} \end{pmatrix}.$$

Note that the first index is the row index and the second index is the column index. The set of  $N \times M$  real matrices is denoted  $\mathbb{R}^{N \times M}$ , so  $A \in \mathbb{R}^{N \times M}$ . The  $(i, j)$ -element of  $A$  is denoted  $[A]_{i,j}$  or sometimes (like above) just  $a_{ij}$ .

**MATLAB:** To define a matrix  $A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$ , type `A=[1,2;3,4]`

# 1 Numbered section

## 1.1 Numbered subsection

### 1.1.1 Numbered subsubsection

## Section

### Subsection

#### Subsubsection

Unnumbered equation:

$$e^{-(x-x')^2/(2\sigma^2)}.$$

Numbered equation:

$$e^{i\pi} = -1 \tag{1}$$

Equation 1 is the most beautiful thing in the universe, as explained in [1]. If you have a citation database, you can also use `bibtex`. It is always good to include some figures, too, especially pretty ones like Figure 1.

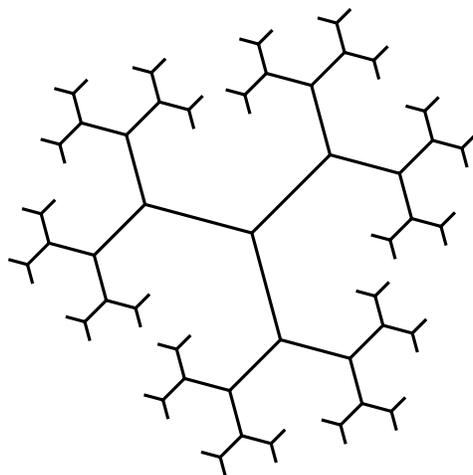


Figure 1: Part of a three-regular tree

If you want to align equations, use `eqnarray`

$$1 = \alpha_1 + \alpha_2 \tag{2}$$

$$-1 = \alpha_1 - \alpha_2. \tag{3}$$

If the reason you need a multiline display is that your equation is too long, you can also use `multline` to split it:

$$K(i, j) = K_R^{(k)}(d(i, j)) = \frac{1}{2} \pi(k-1) \int_0^\pi \frac{e^{-\beta \left(1 - \frac{2\sqrt{k-1}}{k} \cos x\right)}}{k^2 - 4(k-1) \cos^2 x} \cdot \tanh \left( \frac{1}{1 + \frac{1}{1 + \arctan \beta}} \right) \sin x [(k-1) \sin(d+1)x - \sin(d-1)x] dx$$

Don't forget to put a little bit of space `,` for example `\,` before the `dx`!

To include text fixed with and with no formatting, use the `verbatim` package. If you need just a few symbols, like in this sentence, use the special form `\verb#<text goes here>#`.

