

Employing hidden Markov models of neural spike-trains toward the improved estimation of linear receptive fields and the decoding of multiple firing regimes

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# LNP Model Overview

- Linear-nonlinear-Poisson
  - Stimuli are passed through a linear filter
    - The linear filter is the neuron's receptive field
  - The result is passed through a nonlinearity to determine the instantaneous firing rate
  - The rate defines an inhomogeneous Poisson process

$$\lambda(t) = f_{\phi}(\vec{k} \cdot \vec{s}(t))$$
$$p(\text{spike in } t, t + dt) = \lambda(t) dt$$
$$p(\text{no spike}) = e^{-\lambda(t) dt}$$

# LNP Model Learning

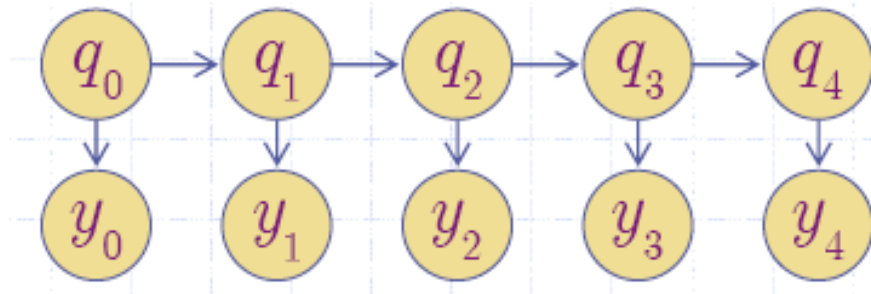
- Model parameters are learned by maximizing the log-likelihood
  - If  $f_\phi$  is convex and log-concave, there is a unique solution easily found by gradient ascent
  - It doesn't matter your  $f_\phi$  is wrong

$$L(\theta) \sim \sum_{i \in \text{spikes}} \log f_\phi(\vec{k} \cdot \vec{s}(t_i)) - \int f_\phi(\vec{k} \cdot \vec{s}(t)) dt$$

# HMM Overview

- Bayesian network model
- 2 events at every time-step (discrete model)
  - Transition to next step (hidden)
  - Emit observable (known)
- Emission probability distributions vary from state to state (in general)
  - Therefore, can infer underlying sequence of hidden states from sequence of observables
- Uses the Markov assumption
  - The future is independent of the past given the present

- Graphical model:



- Markov assumption:

$$\text{future} \perp\!\!\!\perp \text{past} \mid \text{present}$$

$$p(q_t \mid q_{t-1}, q_{t-2}, \dots, q_1, q_0) = p(q_t \mid q_{t-1})$$

- Factorized complete probability distribution  $X_U = \{y_{(0,T)}, q_{(0,T)}\}$ :

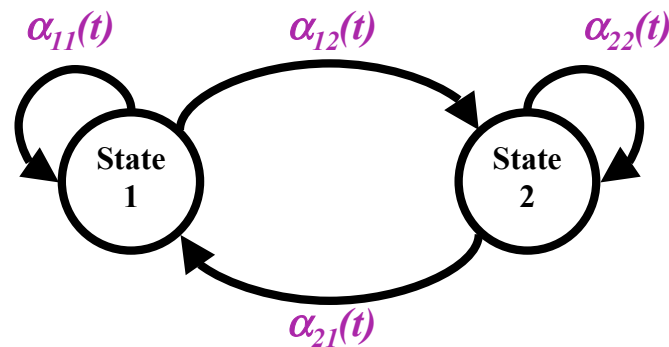
$$p(X_U) = p(q_0) \prod_{t=1}^T p(q_t \mid q_{t-1}) \prod_{t=0}^T p(y_t \mid q_t)$$

# Improving RF estimation

- Original question:
  - Can we improve receptive field estimation by categorizing spikes as either informative or not informative about the stimulus, and then only use the relevant spikes to calculate the RF?
- HMM version:
  - Can we learn when the neuron is in a stimulus attentive state and when it is in some ‘other’ state?

# A 2-state model

- State 1: Attending to stimulus
- State 2: Attending to “other” activity
- Biologically reasonability:
  - UP/DOWN states
  - Tonic-burst LGN neurons



- Transition matrix:

- Defined by rates is in LNP model

- $$\alpha(t) = \begin{pmatrix} e^{-g_\phi(\vec{k}'_{12} \cdot \vec{s}(t))dt} & g_\phi(\vec{k}'_{12} \cdot \vec{s}(t))dt \\ g_\phi(\vec{k}'_{21} \cdot \vec{s}(t))dt & e^{-g_\phi(\vec{k}'_{21} \cdot \vec{s}(t))dt} \end{pmatrix}$$

- Emission matrix:

- LNP model for state-1 (stimulus dependent)
- Homogeneous Poisson process for state-2

- $$\eta(t) = \begin{pmatrix} f_\phi(\vec{k}_s \cdot \vec{s}(t))dt & e^{-f_\phi(\vec{k}_s \cdot \vec{s}(t))dt} \\ \lambda_o dt & e^{-\lambda_o dt} \end{pmatrix}$$

- Model parameters:

- $\vec{k}'_{12}$ 
  - Linear filter for transitioning while in state-1
- $\vec{k}'_{21}$ 
  - Linear filter for transitioning while in state-2
- $\vec{k}_s$ 
  - The neuron's receptive field



# HMM Max Likelihood

- Since we don't know the hidden variables, we can't maximize the complete log-likelihood
- Incomplete likelihood:

- $$L(\theta) = \log \sum_{q_{(0,T)}} \pi_{q_0} \prod_{i=1}^T \alpha_{q_{i-1}q_i}(t_i) \prod_{i=0}^T \eta_{q_i y_i}(t_i)$$

- Exponential in  $T$

- Use Expectation-Maximization

- E-step: Guess the  $q_i$ 's at the current parameter settings (Baum-Welch)
  - M-step: Maximize the complete log-likelihood using the guessed  $q_i$ 's
  - EM is guaranteed to monotonically increase the incomplete log-likelihood
  - M-step is concave if  $g_\phi$  and  $f_\phi$  are convex and log-concave

# Algorithmic considerations

- Convergence can be slow
  - EM can have linear convergence near the maximum likelihood solution
    - Usually quadratic convergence
  - It is possible to perform gradient ascent directly on the log-likelihood
    - The exact gradient can be calculated
    - This provides quadratic convergence
  - The best approach is to switch between EM and GA depending on the local likelihood landscape
  - Using a continuous time formulation can also help
    - In discrete time the probabilities for all time-steps must be calculated
      - You can easily have data with  $> 1e7$  time-steps
      - Almost all time-steps have no associated spikes
    - In continuous time the probabilities are integrated from spike-time to spike-time
      - This involves much less computation and memory

- Computations can be numerically unstable
  - Bernoulli approximation to Poisson distribution may fail when transition and firing rates get too high

- $\lambda(t)dt + e^{-\lambda(t)dt} \neq 1$

- It's okay to use to true Poisson distribution for firing (i.e. you can have more than 1 spike in a time-step)

- $\eta(t_i) = \frac{(\lambda(t_i)dt)^{y_i} e^{-\lambda(t_i)dt}}{y_i!}$

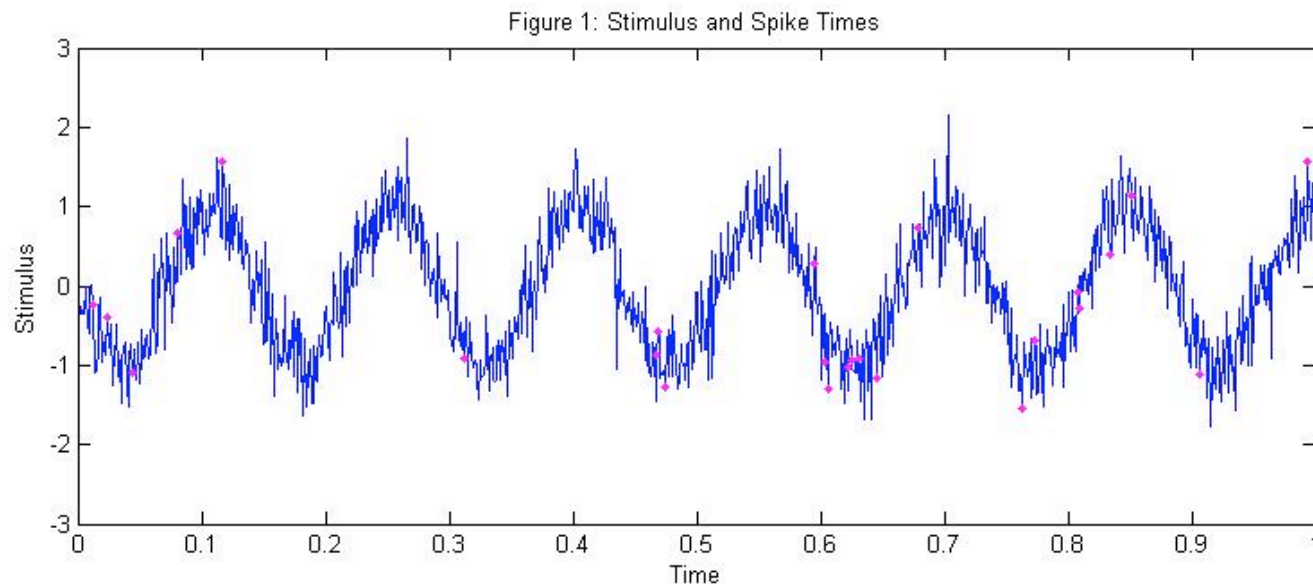
- The transition probabilities must be changed since it makes no sense to have more than 1 transition in a single time-step

- $\alpha(t) = \begin{pmatrix} \frac{1}{1 + g_\varphi(\bar{k}'_{12} \cdot \bar{s}(t))dt} & \frac{g_\varphi(\bar{k}'_{12} \cdot \bar{s}(t))dt}{1 + g_\varphi(\bar{k}'_{12} \cdot \bar{s}(t))dt} \\ \frac{g_\varphi(\bar{k}'_{21} \cdot \bar{s}(t))dt}{1 + g_\varphi(\bar{k}'_{21} \cdot \bar{s}(t))dt} & \frac{1}{1 + g_\varphi(\bar{k}'_{21} \cdot \bar{s}(t))dt} \end{pmatrix}$

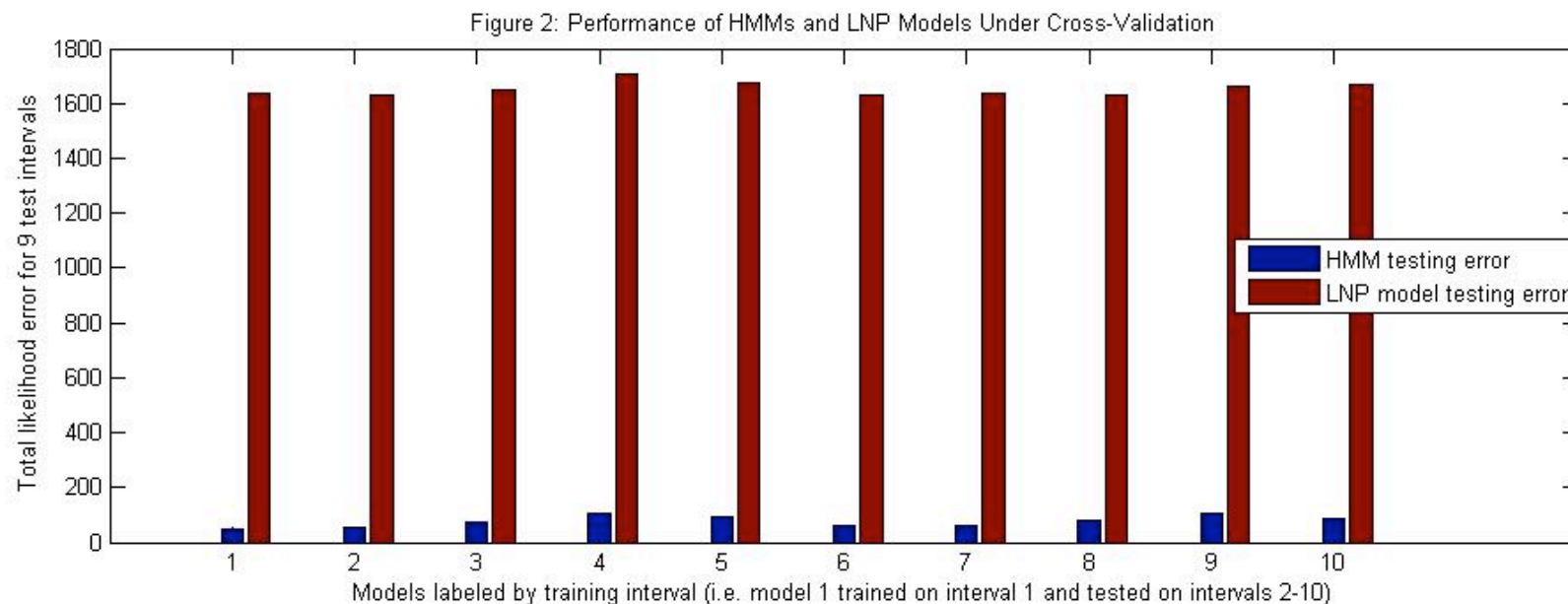
- To guarantee concavity of M-step,  $g_\varphi$  must grow exponentially
  - A continuous time formulation also solves this problem since it guarantees that the Bernoulli approximation is correct
  - As  $dt \rightarrow 0$ , the new discrete formulation and the continuous formulation are equivalent

# Preliminary Results

- I simulated 100 seconds of data
  - 1d, noisy sine-wave stimulus
  - $\vec{k}'_{12}$  likes positive stimulus values
  - $\vec{k}'_{21}$ ,  $\vec{k}_s$  like negative stimulus values
  - Firing rate in state-1: ~20 Hz
  - Firing rate in state-2: 10 Hz
  - All nonlinearity were the exponential  $e^u$



- The data were partitioned into ten 10 second segments.
- 10 HMMs and 10 standard LNP models were trained, 1 on each segment
- The remaining 9 segments were used to test the models
- The log-likelihoods shown are the total difference while testing from the log-likelihood achieved by the HMM trained on that segment
- All the HMMs outperformed all the LNP models on all segments



- After training, the inferred hidden state values show that the model did learn to distinguish state-1 from state-2
- There are 4 important combinations to predict
- Trivially (since the average firing rate is higher in state-1, and state-2 is more common):
  - Being in state-1 and spiking (i.e. 0.91 s)
  - Being in state-2 and not-spiking (i.e. 0.97 s)
- Not-trivially:
  - Being in state-2 and spiking (i.e. 0.98 s)
  - Being in state-1 and not spiking (shown elsewhere)

Figure 3: Predicted and True Hidden State Values

