

## Advanced Computer Graphics (Spring 2006)

COMS 4162, Lecture 3: Sampling and Reconstruction

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## To Do

- Assignment 1, Due Feb 16.
  - Anyone need help finding partners?
  - Start thinking about written part based on this lecture

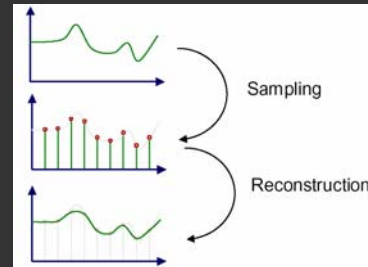
## Outline

- Basic ideas of sampling, reconstruction, aliasing
- Signal processing and Fourier analysis
- Implementation of digital filters (second part of assn next week)
- Section 14.10 of textbook (you really should read it)

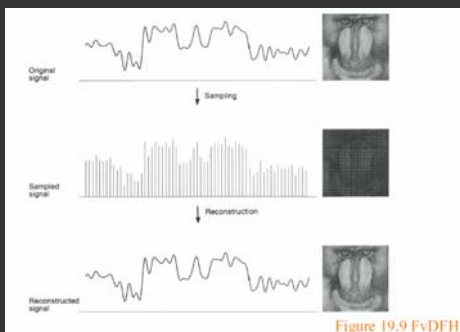
Some slides courtesy Tom Funkhouser

## Sampling and Reconstruction

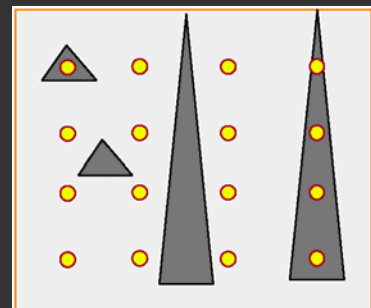
- An image is a 2D array of samples
- Discrete samples from real-world continuous signal



## Sampling and Reconstruction

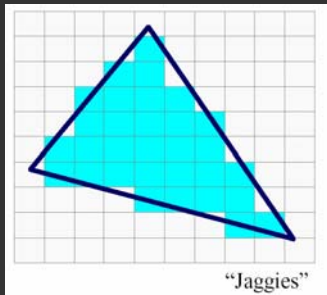


## (Spatial) Aliasing



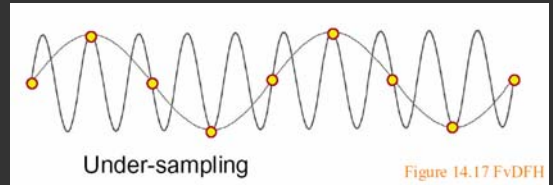
## (Spatial) Aliasing

- Jaggies probably biggest aliasing problem

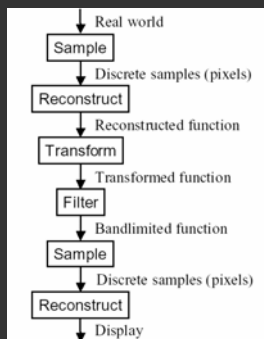


## Sampling and Aliasing

- Artifacts due to undersampling or poor reconstruction
- Formally, high frequencies masquerading as low
- E.g. high frequency line as low freq jaggies



## Image Processing pipeline



## Outline

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## Motivation

- Formal analysis of sampling and reconstruction
- Important theory (signal-processing) for graphics
- Mathematics tested in written assignment
- Will implement some ideas in project

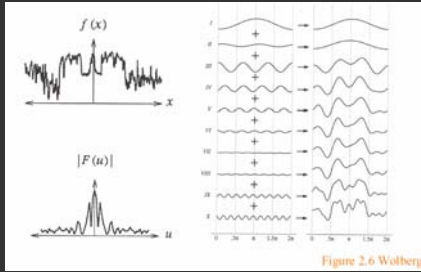
## Ideas

- Signal (function of time generally, here of space)
- Continuous: defined at all points; discrete: on a grid
- High frequency: rapid variation; Low Freq: slow variation
- Images are converting continuous to discrete. Do this sampling as best as possible.
- Signal processing theory tells us how best to do this
- Based on concept of frequency domain Fourier analysis

## Sampling Theory

Analysis in the frequency (not spatial) domain

- Sum of sine waves, with possibly different offsets (phase)
- Each wave different frequency, amplitude



## Fourier Transform

- Tool for converting from spatial to frequency domain
- Or vice versa
- One of most important mathematical ideas
- Computational algorithm: Fast Fourier Transform
  - One of 10 great algorithms scientific computing
  - Makes Fourier processing possible (images etc.)
  - Not discussed here, but see extra credit on assignment 1

## Fourier Transform

- Simple case, function sum of sines, cosines

$$f(x) = \sum_{u=-\infty}^{+\infty} F(u)e^{2\pi iux}$$

$$F(u) = \int_0^{2\pi} f(x)e^{-2\pi iux} dx$$

- Continuous infinite case

Forward Transform:  $F(u) = \int_{-\infty}^{\infty} f(x)e^{-2\pi iux} dx$

Inverse Transform:  $f(x) = \int_{-\infty}^{\infty} F(u)e^{2\pi iux} du$

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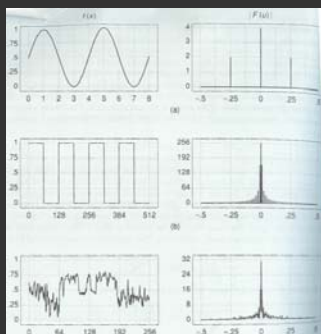
- Discrete case

$$F(u) = \sum_{x=0}^{x=N-1} f(x) [\cos(2\pi ux / N) - i \sin(2\pi ux / n)], \quad 0 \leq u \leq N-1$$

$$f(x) = \frac{1}{N} \sum_{u=0}^{u=N-1} F(u) [\cos(2\pi ux / N) + i \sin(2\pi ux / n)], \quad 0 \leq x \leq N-1$$

## Fourier Transform: Examples 1

Single sine curve  
(+constant DC term)



$$f(x) = \sum_{u=-\infty}^{+\infty} F(u)e^{2\pi iux}$$

$$F(u) = \int_0^{2\pi} f(x)e^{-2\pi iux} dx$$

## Fourier Transform Examples 2

Forward Transform:  $F(u) = \int_{-\infty}^{\infty} f(x)e^{-2\pi iux} dx$

Inverse Transform:  $f(x) = \int_{-\infty}^{+\infty} F(u)e^{2\pi iux} du$

- Common examples

$f(x)$	$F(u)$
$\delta(x - x_0)$	$e^{-2\pi iux_0}$
1	$\delta(u)$
$e^{-ax^2}$	$\sqrt{\pi/a} e^{-\pi^2 u^2 / a}$

## Fourier Transform Properties

Forward Transform:  $F(u) = \int_{-\infty}^{\infty} f(x)e^{-2\pi iux} dx$

Inverse Transform:  $f(x) = \int_{-\infty}^{\infty} F(u)e^{2\pi iux} du$

- Common properties

- Linearity:  $F(af(x) + bg(x)) = aF(f(x)) + bF(g(x))$

- Derivatives: [integrate by parts]  $F(f'(x)) = \int_{-\infty}^{\infty} f'(x)e^{-2\pi iux} dx = 2\pi iuF(u)$

- 2D Fourier Transform

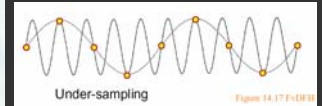
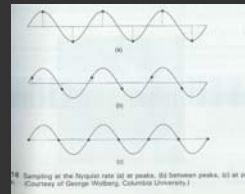
Forward Transform:  $F(u, v) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y)e^{-2\pi iux} e^{-2\pi ivy} dx dy$

- Convolution (next)

Inverse Transform:  $f(x, y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(u, v)e^{2\pi iux} e^{2\pi ivy} dudv$

## Sampling Theorem, Bandlimiting

- A signal can be reconstructed from its samples, if the original signal has no frequencies above half the sampling frequency – Shannon
- The minimum sampling rate for a bandlimited function is called the Nyquist rate



## Sampling Theorem, Bandlimiting

- A signal can be reconstructed from its samples, if the original signal has no frequencies above half the sampling frequency – Shannon
- The minimum sampling rate for a bandlimited function is called the Nyquist rate
- A signal is bandlimited if the highest frequency is bounded. This frequency is called the bandwidth
- In general, when we transform, we want to filter to bandlimit before sampling, to avoid aliasing

## Antialiasing

- Sample at higher rate
  - Not always possible
  - Real world: lines have infinitely high frequencies, can't sample at high enough resolution
- Prefilter to bandlimit signal
  - Low-pass filtering (blurring)
  - Trade blurriness for aliasing

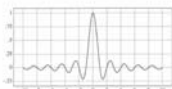
## Ideal bandlimiting filter

- Formal derivation is homework exercise

- Frequency domain



- Spatial domain



$$\text{Sinc}(x) = \frac{\sin \pi x}{\pi x}$$

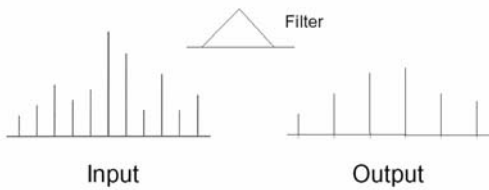
Figure 4.5 Wolberg

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  - Convolution
- Implementation of digital filters (second part of assn next week)
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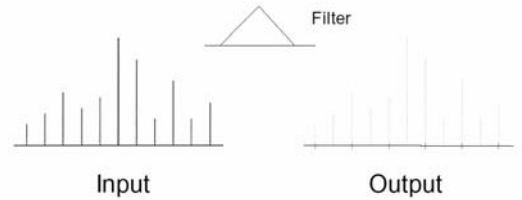
## Convolution 1

- Spatial domain: output pixel is weighted sum of pixels in neighborhood of input image
  - Pattern of weights is the "filter"



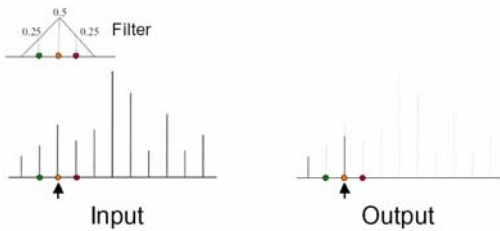
## Convolution 2

- Example 1:



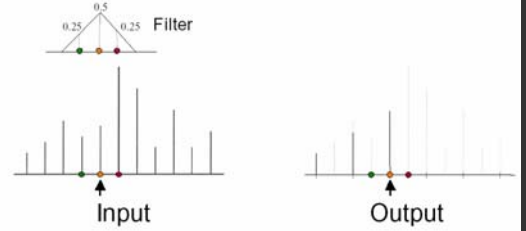
## Convolution 3

- Example 1:



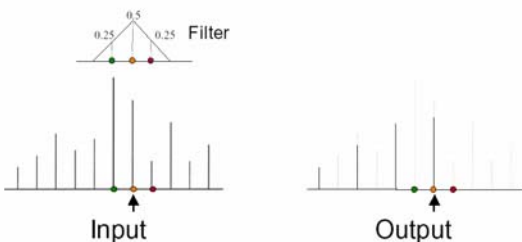
## Convolution 4

- Example 1:



## Convolution 5

- Example 1:



## Convolution in Frequency Domain

$$\text{Forward Transform: } F(u) = \int_{-\infty}^{+\infty} f(x)e^{-2\pi iux} dx$$

$$\text{Inverse Transform: } f(x) = \int_{-\infty}^{+\infty} F(u)e^{2\pi iux} du$$

- Convolution ( $f$  is signal ;  $g$  is filter [or vice versa])

$$h(y) = \int_{-\infty}^{+\infty} f(x)g(y-x)dx = \int_{-\infty}^{+\infty} g(x)f(y-x)dx$$

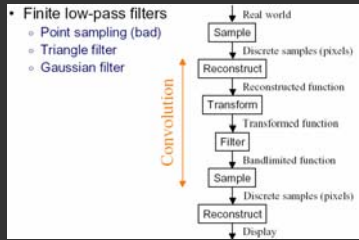
$$h = f * g \text{ or } f \otimes g$$

- Fourier analysis (frequency domain multiplication)

$$H(u) = F(u)G(u)$$

## Practical Image Processing

- Discrete convolution (in spatial domain) with filters for various digital signal processing operations
- Easy to analyze, understand effects in frequency domain
  - E.g. blurring or bandlimiting by convolving with low pass filter



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