Computer Graphics (Fall 2008)

COMS 4160, Lecture 7: Curves 2 http://www.cs.columbia.edu/~cs4160

To Do

- Start on HW 2 (cannot be done at last moment)
 This (and previous) lecture should have all information need
- Start thinking about partners for HW 3 and HW 4
 - Remember though, that HW2 is done individually
 - Your submission of HW 2 must include partner for HW 3

Outline of Unit

- Bezier curves (last time)
- deCasteljau algorithm, explicit, matrix (last time)
- Polar form labeling (blossoms)
- B-spline curves
- Not well covered in textbooks (especially as taught here). Main reference will be lecture notes. If you do want a printed ref, handouts from CAGD, Seidel

Idea of Blossoms/Polar Forms

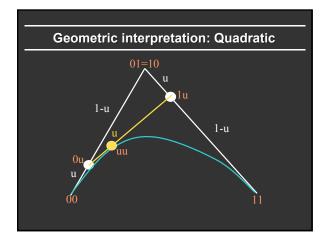
- (Optional) Labeling trick for control points and intermediate deCasteljau points that makes thing intuitive
- E.g. quadratic Bezier curve F(u)
 - Define auxiliary function $f(u_1,u_2)$ [number of args = degree]
 - Points on curve simply have $u_1 = u_2$ so that F(u) = f(u,u)
 - And we can label control points and deCasteljau points not on curve with appropriate values of (u₁,u₂)

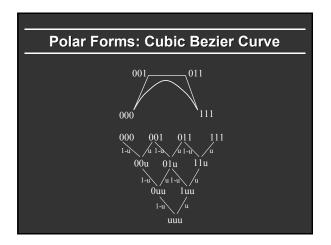


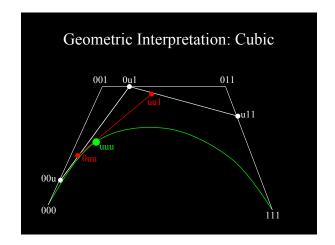
Idea of Blossoms/Polar Forms

- Points on curve simply have $u_1=u_2$ so that F(u)=f(u,u)
- f is symmetric f(0,1) = f(1,0)
- Only interpolate linearly between points with one arg different
 f(0,u) = (1-u) f(0,0) + u f(0,1) Here, interpolate f(0,0) and f(0,1)=f(1,0)









Why Polar Forms?

- Simple mnemonic: which points to interpolate and how in deCasteljau algorithm
- Easy to see how to subdivide Bezier curve (next) which is useful for drawing recursively
- Generalizes to arbitrary spline curves (just label control points correctly instead of 00 01 11 for Bezier)
- Easy for many analyses (beyond scope of course)

Subdividing Bezier Curves

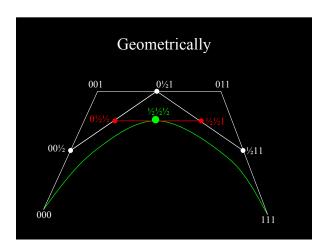
Drawing: Subdivide into halves $(u = \frac{1}{2})$ Demo:

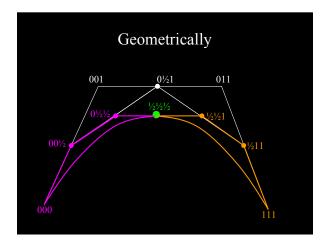
- Recursively draw each piece
- At some tolerance, draw control polygon
 Trivial for Bezier curves (from deCasteljau algorithm): hence widely used for drawing



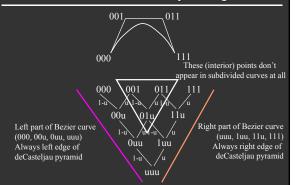
Why specific labels/ control points on left/right?

How do they follow from deCasteljau?





Subdivision in deCasteljau diagram



Summary for HW 2

- Bezier2 (Bezier discussed last time)
- Given arbitrary degree Bezier curve, recursively subdivide for some levels, then draw control polygon hw2.exe
- Generate deCasteljau diagram; recursively call a routine with left edge and right edge of this diagram
- You are given some code structure; you essentially just need to compute appropriate control points for left, right

DeCasteljau: Recursive Subdivision

Input: Control points C_i with $0 \le i \le n$ where n is the degree. Output: L_i , R_i for left and right control points in recursion.

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1 for (level = n \; ; level \ge 0 \; ; level - -)  { 2 if (level = = n) \; \{ / / | \text{Initial control points} \} 3 \forall i : 0 \le i \le n : p_i^{level} = C_i \; ; \text{continue} \; ; \} 4 for (i = 0 \; ; i \le level \; ; i + +) 5 p_i^{level} = \frac{1}{2} * (p_i^{level+1} + p_{i+1}^{level+1}) \; ; 6 } 7 \forall i : 0 \le i \le n : L_i = p_i^i : R_i = v^i :
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- DeCasteljau (from last lecture) for midpoint
- Followed by recursive calls using left, right parts

Outline of Unit

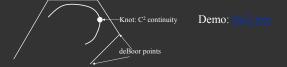
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Bezier: Disadvantages

- Single piece, no local control (move a control point, whole curve changes) hw2.exe
- Complex shapes: can be very high degree, difficult
- In practice, combine many Bezier curve segments
 - But only position continuous at join since Bezier curves interpolate end-points (which match at segment boundaries)
 - Unpleasant derivative (slope) discontinuities at end-points
 - Can you see why this is an issue?

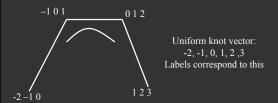
B-Splines

- Cubic B-splines have C² continuity, local control
- 4 segments / control point, 4 control points/segment
- Knots where two segments join: Knotvector
- Knotvector uniform/non-uniform (we only consider uniform cubic B-splines, not general NURBS)



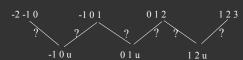
Polar Forms: Cubic Bspline Curve

- Labeling little different from in Bezier curve
- No interpolation of end-points like in Bezier
- Advantage of polar forms: easy to generalize



deCasteljau: Cubic B-Splines

- Easy to generalize using polar-form labels
- -1 0 1 012 123 -2 -1 0
- Impossible remember without



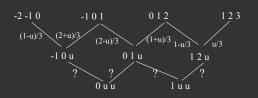
deCasteljau: Cubic B-Splines

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-2 -1 0

1 2 3

- Easy to generalize using polar-form labels
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deCasteljau: Cubic B-Splines

- Easy to generalize using polar-form labels
- Impossible remember without



-2 -1 0

1 2 3

Explicit Formula (derive as exercise)

$$F(u) = [u^{3} u^{2} u \, 1] M \begin{bmatrix} P0 \\ P1 \\ P2 \\ P3 \end{bmatrix} \qquad M = \frac{1}{6} \begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{bmatrix}$$

$$\begin{array}{c} P0 & P1 & P2 & P3 \\ -2 - 1 \, 0 & -1 \, 0 \, 1 & 0 \, 1 \, 2 & 1 \, 2 \, 3 \\ \hline (1-u)/3 & (2+u)/3 & (2-u)/3 & (1+u)/3 & 1-u/3 & u/3 \\ \hline & -1 \, 0 \, u & 0 \, 1 \, u & 1 \, 2 \, u \\ \hline & 0 \, u \, u & 1-u & u \, u \, u & u \end{array}$$

Summary of HW 2

- BSpline Demo
- Arbitrary number of control points / segments
 - Do nothing till 4 control points (see demo) Number of segments = # cpts 3
- Segment A will have control pts A,A+1,A+2,A+3
- Evaluate Bspline for each segment using 4 control points (at some number of locations, connect lines)
- Use either deCasteljau algorithm (like Bezier) or explicit form [matrix formula on previous slide]
- Questions?