Computer Graphics (Fall 2004)

COMS 4160, Lecture 7: Curves 2

http://www.cs.columbia.edu/~cs4160

To Do

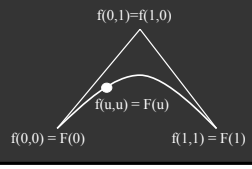
- Start on HW 2
  This (and previous) lecture should have all information need
- Start thinking about partners for HW 3 and HW 4
  - Remember though, that HW2 is done individually
  - Your submission of HW 2 must include partner for HW 3

Outline of Unit

- Bezier curves (last time)
- deCasteljau algorithm, explicit, matrix (last time)
- *Polar form labeling (blossoms)*
- B-spline curves
- Not well covered in textbooks (especially as taught here). Main reference will be lecture notes. If you do want a printed ref, handouts from CAGD, Seidel

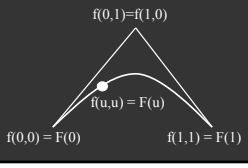
Idea of Blossoms/Polar Forms

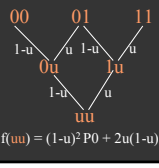
- (Optional) Labeling trick for control points and intermediate deCasteljau points that makes thing intuitive
- E.g. quadratic Bezier curve F(u)
  - Define auxiliary function $f(u_1,u_2)$ [number of args = degree]
  - Points on curve simply have $u_1=u_2$ so that F(u) = f(u,u)
  - And we can label control points and deCasteljau points not on curve with appropriate values of (u_1,u_2)



Idea of Blossoms/Polar Forms

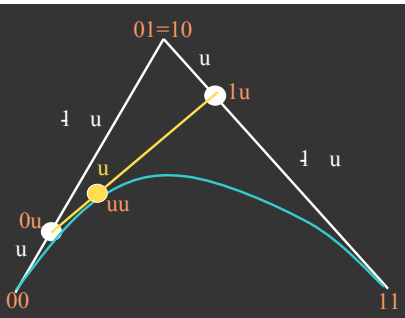
- Points on curve simply have $u_1=u_2$ so that F(u) = f(u,u)
- f is symmetric f(0,1) = f(1,0)
- Only interpolate linearly between points with one arg different
  - f(0,u) = (1-u) f(0,0) + u f(0,1) Here, interpolate f(0,0) and f(0,1)=f(1,0)



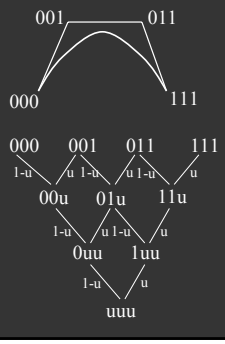


F(u) = f(uu) = $(1-u)^2$ P0 + 2u(1-u) P1 + u^2 P2

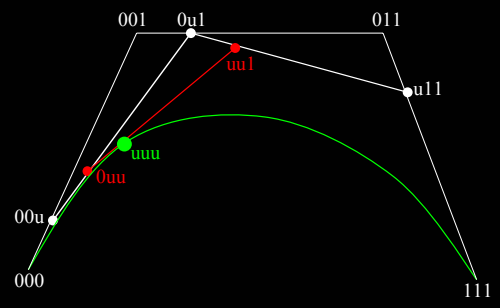
Geometric interpretation: Quadratic



Polar Forms: Cubic Bezier Curve



Geometric Interpretation: Cubic



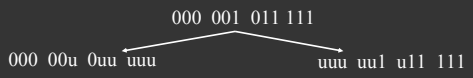
Why Polar Forms?

- Simple mnemonic: which points to interpolate and how in deCasteljau algorithm
- *Easy to see how to subdivide Bezier curve (next) which is useful for drawing recursively*
- Generalizes to arbitrary spline curves (just label control points correctly instead of 00 01 11 for Bezier)
- Easy for many analyses (beyond scope of course)

Subdividing Bezier Curves

Drawing: Subdivide into halves (u = ½) Demo: hw2.exe

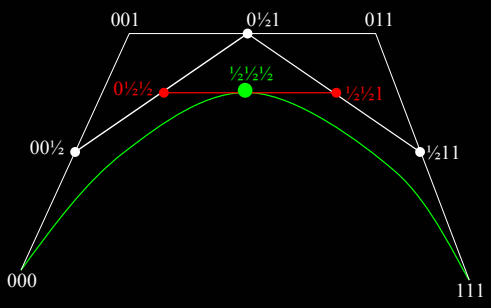
- Recursively draw each piece
- At some tolerance, draw control polygon
- Trivial for Bezier curves (from deCasteljau algorithm): hence widely used for drawing



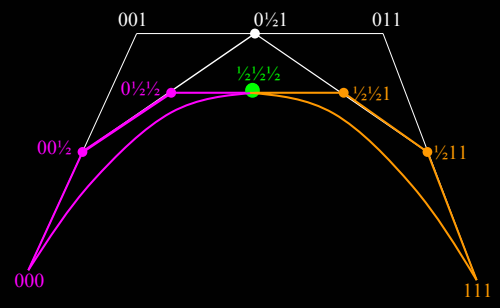
Why specific labels/ control points on left/right?

- How do they follow from deCasteljau?

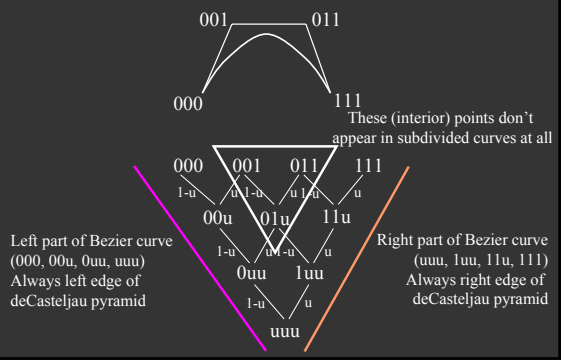
Geometrically



Geometrically



Subdivision in deCasteljau diagram



Summary for HW 2

- Bezier2 (Bezier discussed last time)
- Given arbitrary degree Bezier curve, recursively subdivide for some levels, then draw control polygon hw2.exe
- Generate deCasteljau diagram; recursively call a routine with left edge and right edge of this diagram
- You are given some code structure; you essentially just need to compute appropriate control points for left, right
- Questions?

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- *B-spline curves*

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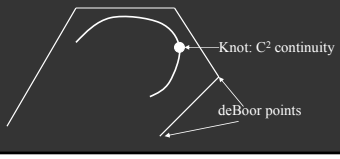
Bezier: Disadvantages

- Single piece, no local control (move a control point, whole curve changes) hw2.exe
- Complex shapes: can be very high degree, difficult
- In practice, combine many Bezier curve segments
  - But only position continuous at join since Bezier curves interpolate end-points (which match at segment boundaries)
  - Unpleasant derivative (slope) discontinuities at end-points
  - Can you see why this is an issue?

B-Splines

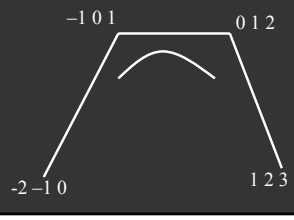
- Cubic B-splines have C^2 continuity, local control
- 4 segments / control point, 4 control points/segment
- Knots where two segments join: Knotvector
- Knotvector uniform/non-uniform (we only consider uniform cubic B-splines, not general NURBS)



Demo: hw2.exe

Polar Forms: Cubic Bspline Curve

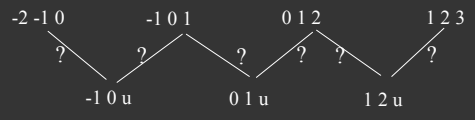
- Labeling little different from in Bezier curve
- No interpolation of end-points like in Bezier
- Advantage of polar forms: easy to generalize



Uniform knot vector:
-2, -1, 0, 1, 2 ,3
Labels correspond to this

deCasteljau: Cubic B-Splines

- Easy to generalize using polar form labels
- Impossible remember without



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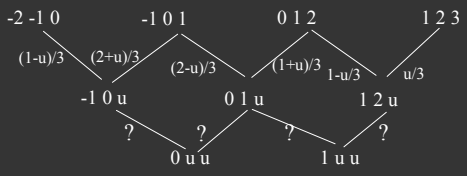

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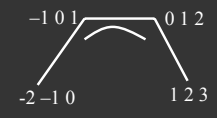
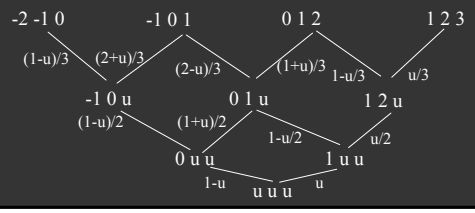
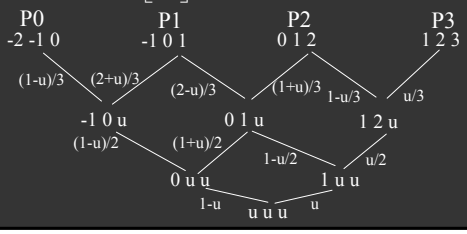




Explicit Formula (derive as exercise)

$$F(u) = [u^3\ u^2\ u\ 1]M\begin{bmatrix} P0 \\ P1 \\ P2 \\ P3 \end{bmatrix} \qquad M = \frac{1}{6}\begin{bmatrix} -1 & 3 & -3 & 1 \\ 3 & -6 & 3 & 0 \\ -3 & 0 & 3 & 0 \\ 1 & 4 & 1 & 0 \end{bmatrix}$$



Summary of HW 2

- BSpline Demo hw2.exe
- Arbitrary number of control points / segments
  - Do nothing till 4 control points (see demo)
  - Number of segments = # cpts – 3
- Segment A will have control pts A,A+1,A+2,A+3
- Evaluate Bspline for each segment using 4 control points (at some number of locations, connect lines)
- Use either deCasteljau algorithm (like Bezier) or explicit form [matrix formula on previous slide]
- Questions?