## Data Structures in Java

Session 16 Instructor: Bert Huang <u>http://www.cs.columbia.edu/~bert/courses/3134</u>

#### Announcements

- Homework 4 due next class
- Midterm grades posted. Avg: 79/90
- Remaining grades:
  - hw4, hw5, hw6 25%
  - Final exam 30%

# Today's Plan

- Graphs
- Topological Sort
- Shortest Path Algorithms: Dijkstra's





# Graph Terminology

- A graph is a set of nodes and edges
  - nodes aka vertices
  - edges aka arcs, links
- Edges exist between pairs of nodes
  - if nodes x and y share an edge, they are adjacent

# Graph Terminology

- Edges may have weights associated with them
- Edges may be **directed** or **undirected**
- A path is a series of adjacent vertices
  - the **length** of a path is the sum of the edge weights along the path (1 if unweighted)
- A cycle is a path that starts and ends on a node

# **Graph Properties**

- An undirected graph with no cycles is a tree
- A directed graph with no cycles is a special class called a directed acyclic graph (DAG)
- In a connected graph, a path exists between every pair of vertices
- A complete graph has an edge between every pair of vertices

## Graph Applications: A few examples

- Computer networks
- The World Wide Web
- Social networks
- Public transportation

- Probabilistic
  Inference
- Flow Charts

#### Implementation

- Option 1:
  - Store all nodes in an indexed list
  - Represent edges with adjacency matrix
- Option 2:
  - Explicitly store adjacency lists

## **Adjacency Matrices**

- 2d-array **A** of boolean variables
- A[i][j] is true when node **i** is adjacent to node **j** 
  - If graph is undirected, A is symmetric (





## Adjacency Lists

 Each node stores references to its neighbors





# Math Notation for Graphs

- Set Notation:
  - $v \in V$  (v is in V)
  - $U \cup V$  (union)
  - $U \cap V$ (intersection)
  - U ⊂ V
    (U is a subset of V)

- $G = \{V, E\}$
- G is the graph
- V is set of vertices
- E is set of edges
- $(v_i, v_j) \in E$
- |V| = N = size of V

# **Topological Sort**

- Problem definition:
  - Given a directed acyclic graph G, order the nodes such that for each edge (v<sub>i</sub>, v<sub>j</sub>) ∈ E,
    v<sub>i</sub> is before v<sub>j</sub> in the ordering.
- e.g., scheduling errands when some tasks depend on other tasks being completed.



#### Topological Sort Naïve Algorithm

- **Degree** means # of edges, indegree means # of incoming edges
- 1. Compute the **indegree** of all nodes
- 2. Print any node with indegree 0
- 3. Remove the node we just printed. Go to 1.
- Which nodes' indegrees change?

#### Topological Sort Better Algorithm

- 1. Compute all indegrees
- 2. Put all indegree 0 nodes into a Collection
- 3. Print and remove a node from Collection
- 4. Decrement indegrees of the node's neighbors.
- 5. If any neighbor has indegree 0, place in Collection. Go to 3.



ATM	comp	grocer- ies	recipe	stamps	taxes	cook	grand- ma	post- card	mail taxes
0	0	2	Ι	Ι	Ι	2	2	Ι	2



ATM	comp	grocer- ies	recipe	stamps	taxes	cook	grand- ma	post- card	mail taxes
-	-	2	Ι	Ι	Ι	2	2	Ι	2



ATM	comp	grocer- ies	recipe	stamps	taxes	cook	grand- ma	post- card	mail taxes
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ATM	comp	grocer- ies	recipe	stamps	taxes	cook	grand- ma	post- card	mail taxes
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# Topological Sort Running time

- Initial indegree computation: O(IEI)
  - Unless we update indegree as we build graph
- IVI nodes must be enqueued/dequeued
- Dequeue requires operation for outgoing edges
- Each edge is used, but never repeated
- Total running time O(IVI + IEI)

#### Shortest Path

- Given G = (V,E), and a node s ∈ V, find the shortest (weighted) path from s to every other vertex in G.
- Motivating example: subway travel
  - Nodes are junctions, transfer locations
  - Edge weights are estimated time of travel

#### Approximate MTA Express Stop Subgraph

• A few inaccuracies (don't use this to plan any trips)



#### **Breadth First Search**

- Like a level-order traversal
- Find all adjacent nodes (level 1)
- Find *new* nodes adjacent to level 1 nodes (level 2)
- ... and so on
- We can implement this with a queue

## Unweighted Shortest Path Algorithm

- Set node s' distance to 0 and enqueue s.
- Then repeat the following:
  - Dequeue node **v**. For unset neighbor **u**:
    - set neighbor u's distance to v's distance +1
    - mark that we reached v from u
    - enqueue **u**



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## Weighted Shortest Path

- The problem becomes more difficult when edges have different weights
- Weights represent different costs on using that edge
- Standard algorithm is **Dijkstra's** Algorithm

## Dijkstra's Algorithm

- Keep distance overestimates D(v) for each node v (all non-source nodes are initially infinite)
- 1. Choose node v with smallest unknown distance
- Declare that v's shortest distance is known
- 3. Update distance estimates for neighbors

# **Updating Distances**

- For each of v's neighbors, w,
- if min(**D(v)+ weight(v,w)**, **D(w)**)
  - i.e., update D(w) if the path going through v is cheaper than the best path so far to w



59 <sup>th</sup> Broad.	Port Auth.	72 <sup>nd</sup> Broad	Times Sq.	Penn St.
inf	inf	inf	inf	0
?	?	?	?	home



59 <sup>th</sup> Broad.	Port Auth.	72 <sup>nd</sup> Broad	Times Sq.	Penn St.
inf	inf	inf	inf	0
?	?	?	?	home



59 <sup>th</sup> Broad.	Port Auth.	72 <sup>nd</sup> Broad	Times Sq.	Penn St.
inf	6	inf	2	0
?	Penn St.?	?	Penn St.?	home



59 <sup>th</sup> Broad.	Port Auth.	72 <sup>nd</sup> Broad	Times Sq.	Penn St.
inf	6	inf	2	0
?	Penn St.?	?	Penn St.	home



59 <sup>th</sup> Broad.	Port Auth.	72 <sup>nd</sup> Broad	Times Sq.	Penn St.
2+12=14	6	2+4=6	2	0
Times Sq?	Penn St.?	Times Sq?	Penn St.	home



59 <sup>th</sup> Broad.	Port Auth.	72 <sup>nd</sup> Broad	Times Sq.	Penn St.
14	6	6	2	0
Times Sq?	Penn St.	Times Sq?	Penn St.	home



59 <sup>th</sup> Broad.	Port Auth.	72 <sup>nd</sup> Broad	Times Sq.	Penn St.
5+6=11	6	6	2	0
Port Auth?	Penn St.	Times Sq?	Penn St.	home



59 <sup>th</sup> Broad.	Port Auth.	72 <sup>nd</sup> Broad	Times Sq.	Penn St.
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59 <sup>th</sup> Broad.	Port Auth.	72 <sup>nd</sup> Broad	Times Sq.	Penn St.
11	6	6	2	0
Port Auth	Penn St.	Times Sq	Penn St.	home

#### Dijkstra's Algorithm Analysis

- First, convince ourselves that the algorithm works.
- At each stage, we have a set of nodes whose shortest paths we know
- In the base case, the set is the source node.
- Inductive step: if we have a correct set, is greedily adding the shortest neighbor correct?

# Proof by Contradiction (Sketch)

- Contradiction: Dijkstra's finds a shortest path to node
  w through v, but there exists an even shorter path
- This shorter path must pass from inside our known set to outside.
- Call the 1<sup>st</sup> node in cheaper path outside our set u



- The path to u must be shorter than the path to w
  - But then we would have chosen **u** instead

#### **Computational Cost**

- Keep a priority queue of all unknown nodes
- Each stage requires a deleteMin, and then some decreaseKeys (the # of neighbors of node)
- We call decreaseKey once per edge, we call deleteMin once per vertex
- Both operations are O(log IVI)
- Total cost: O(IEI log IVI + IVI log IVI) = O(IEI log IVI)

## Reading

• Weiss Section 9.1-9.3 (today's material)