Back in Black: Towards Formal, Black Box Analysis of Sanitizers and Filters

Abstract—We tackle the problem of analyzing filter and sanitizer programs remotely, i.e., given only the ability to query the targeted program and observe the output. We focus on two important and widely used program classes: regular expression (RE) filters and string sanitizers. We demonstrate that existing tools from machine learning that are available for analyzing RE filters, namely automata learning algorithms, require a very large number of queries in order to infer real life RE filters. Motivated by this, we develop the first algorithm that infers symbolic representations of automata in the standard membership/equivalence query model. We show that our algorithm provides an improvement of $x15$ times in the number of queries required to learn real life XSS and SQL filters of popular web application firewall systems such as mod-security and PHPIDS. Active learning algorithms require the usage of an equivalence oracle, i.e., an oracle that tests the equivalence of a hypothesis with the target machine. We show that when the goal is to audit a target filter with respect to a set of attack strings from a context free grammar, i.e., find an attack or infer that none exists, we can use the attack grammar to implement the equivalence oracle with a single query to the filter. Our construction finds on average 90% of the target filter states when no attack exists and is very effective in finding attacks when they are present.

For the case of string sanitizers, we show that existing algorithms for inferring sanitizers modelled as Mealy Machines are not only inefficient, but lack the expressive power to be able to infer real life sanitizers. We design two novel extensions to existing algorithms that allow one to infer sanitizers represented as single-valued transducers. Our algorithms are able to infer many common sanitizer functions such as HTML encoders and decoders. Furthermore, we design an algorithm to convert the inferred models into BEK programs, which allows for further applications such as cross checking different sanitizer implementations and cross compiling sanitizers into different languages supported by the BEK backend. We showcase the power of our techniques by utilizing our black-box inference algorithms to perform an equivalence checking between different HTML encoders including the encoders from Twitter, Facebook and Microsoft Outlook email, for which no implementation is publicly available.

I. INTRODUCTION

Since the introduction and popularization of code injection vulnerabilities as major threats for computer systems, sanitization and filtering of unsafe user input is paramount to the design and implementation of a secure system. Unfortunately, correctly implementing such functionalities is a very challenging task. There is a large literature on attacks and bypasses in implementations both of filter and sanitizer functions [1]–[3].

The importance of sanitizers and filters motivated the development of a number of algorithms and tools [4]–[7] to analyze such programs. More recently, the BEK language [8] was introduced. BEK is a Domain Specific Language (DSL) which allows developers to write string manipulating functions in a language which can then be compiled into symbolic finite state transducers (SFTs). This compilation enables various analysis algorithms for checking properties like commutativity, idempotence and reversibility. Moreover, one can efficiently check whether two BEK programs are equal and, in the opposite case to obtain a string in which the two programs differ.

The BEK language offers a promising direction for the future development of sanitizers where the programs developed for sanitization will be formally analyzed in order to verify that certain desired properties are present. However, the vast majority of code is still written in languages like PHP/Java and others. In order to convert the sanitizers from these languages to BEK programs a significant amount of manual effort is required. Even worst, BEK is completely unable to reason for sanitizers whose source code is not available. This significantly restricts the possibilities for applying BEK to find real life problems in deployed sanitizers.

In this paper we tackle the problem of black-box analysis of sanitizers and filters. We focus our analysis on regular expression filters and string sanitizers which are modelled as finite state transducers. Although regular expression filters are considered suboptimal choices for building robust filters [9], their simplicity and efficiency makes them a very popular option especially for the industry.

Our analysis is black-box, that is, without access to any sort of implementation or source code. We only assume the ability to query a filter/sanitizer and obtain the result. Performing a black-box analysis presents a number of advantages; firstly, our analysis is generic, i.e. independent of any programming language or system. Therefore, our system can be readily applied to any software, without the need for a large engineering effort to adjust the algorithms and implementation into a new programming language. This is especially important since in today’s world, the number of programming languages used varies significantly. To give an example, there are over 15 different programming languages used in the backend of the 15 most popular websites [10].

The second advantage of performing a black-box analysis comes out of necessity rather than convenience. Many times, access to the source code of the program to be analyzed is unavailable. There are multiple reasons this may happen; for one, the service might be reluctant to share the source code
of its product website even with a trusted auditor. This is the reason that a large percentage of penetration tests are performed in a black-box manner. Furthermore, websites such as the ones encountered in the deep web, for example TOR hidden services, are designed to remain as hidden as possible. Finally, software running in hardware systems such as smart cards is also predominately analyzed in a black-box manner.

Our algorithms come with a formal analysis; for every algorithm we develop, we provide a precise description of the conditions and assumptions under which the algorithm will work within a given time bound and provide a correct model of the target filter or sanitizer.

Our goal is to build algorithms that will make it easier for an auditor to understand the functionality of a filter or sanitizer program without access to its source code. We begin by evaluating the most common machine learning algorithms which can be used for this task. We find that these algorithms are not fit for learning filters and sanitizers for different reasons: The main problem in inferring regular expressions with classical automata inference algorithms is the explosion in the number of queries caused by the large alphabets over which the regular expressions are defined. This problem also occurs in the analysis of regular expressions in program analysis applications (whitebox analysis), which motivated the development of the class of symbolic finite automata which effectively handles these cases [11]. Motivated by these advances, we design the first algorithm that infers symbolic finite automata (SFA) in the standard active learning model of membership and equivalence queries. We evaluate our algorithm in 15 real life regular expression filters and show that our algorithm utilizes the number of queries caused by the large alphabets over which the regular expressions are defined. This problem also occurs in...

The astute reader will counter that an equivalence oracle (i.e., an oracle that one submits a hypothesized model and a counterexample is returned if there exists one) is not available in remote testing and thus it has to be simulated at potentially great cost in terms of number of queries. In order to address this we develop a structured approach to equivalence oracle simulation that is based on a given context free grammar $G$. Our learning algorithm will simulate equivalence queries by drawing a single random string $w$ from $\mathcal{L}(G) \setminus \mathcal{L}(H)$ where $\mathcal{L}(H)$ is the language of the hypothesis. If $w$ belongs to the target we have our counterexample, while if not, we have found a string $w$ that is not recognized by the target. In our setting strings that are not recognized by the target filter can be very valuable: we set $G$ to be a grammar of attack strings and we turn the failure of our equivalence oracle simulation to the discovery of a filter bypass! This also gives rise to what we call Grammar Oriented Filter Auditing (GOFA): our learning algorithm, equipped with a grammar of attack strings, can be used by a remote auditor of a filter to either find a vulnerability or obtain a model of the filter (in the form of an SFA) that can be used for further (whitebox) testing and analysis.

Turning our attention to sanitizers, we observe that inferring finite state transducers suffers from even more fundamental problems. Current learning algorithms infer models as Mealy machines, i.e. automata where at each transition one input symbol is consumed and one output symbol is produced. However, this model is very weak in capturing the behavior of real life sanitizers where for each symbol consumed multiple, or none, symbols are produced. Even worse, many modern sanitizers employ a “lookahead”, i.e. they read many symbols from the input before producing an output symbol. In order to model such behavior the inferred transducers must be non deterministic. To cope with these problems we make three contributions: First, we show how to improve the query complexity of the Shabaz-Groz algorithm [12] exponentially. Second, we design an extension of the Shabaz-Groz algorithm which is able to handle transducers which output multiple or no symbols in each transition. Finally, we develop a new algorithm, based on our previous extension, which is able to infer sanitizers that employ a lookahead, i.e., base their current output by reading ahead more than one symbol.

To enable more fine grained analysis of our inferred models we develop an algorithm to convert (symbolic) finite transducers with bounded lookahead into BEK programs. This algorithm enables an interesting application: In the original BEK paper [8] the authors manually converted different HTML encoder implementations into BEK programs and then used the BEK infrastructure to check equivalence and other properties. Our algorithms enable these experiments to be performed automatically, i.e. without manually converting each implementation to a BEK program and more importantly, being agnostic of the implementation details. In fact, we checked seven HTML encode implementations: three PHP implementations, one implementation from the AntiXSS library in .NET and we also included models inferred from the HTML encoders used by the websites of Twitter and Facebook and by the Microsoft Outlook email service. We detected differences between many implementations and found that Twitter and Facebook’s HTML encoders match the htmlspecialcharacters function of PHP although the Outlook service encoder does not match the MS AntiXSS implementation in .NET. Moreover, we found that only one of these implementations is idempotent.

Finally, we point out that although our algorithms are focused on the analysis of sanitizers and filters they are general enough to potentially being applied in a number of different domains. For example, in appendix D, we show how one can use an SFA to model decision trees over the reals. In another application, Doupe et al. [13] create a state aware vulnerability scanner, where they model the different states of the application using a Mealy machine. In their paper they mention they considered utilizing inference techniques for Mealy machines but that this was infeasible, due to the large number of transitions. However, our symbolic learning algorithms are able to handle efficiently exactly those cases and thus, we believe several projects will be able to benefit from our techniques.

A. Limitations

Since the analysis we perform is black-box, all of our techniques are necessarily incomplete. Specifically, there might be some aspect of the target program that our algorithms will fail to discover. Our algorithms are not designed to find, for example, backdoors in filters and sanitizers where a “magic string” is causing the program to enter a hidden state. Such programs will necessarily require an exponential number of queries in the worst case in order to analyze completely. Moreover, our algorithms are not geared towards discovering new attacks for certain vulnerability classes. We assume that
the description of the attack strings for a certain vulnerability
class, for example XSS, is given in the form of a context free
grammar.

B. Contributions

To summarize, our paper makes the following contributions:

Learning Algorithms: We present the first, to the best of
our knowledge, algorithm that learns symbolic finite automata
in the standard membership and equivalence query model.
Furthermore, we improve the query complexity of the Shabaz-Groz algorithm [12], a popular Mealy machine learning
algorithm and present an extension of the algorithm capable
of handling Mealy Machines with ε-input transitions. Finally,
we present a novel algorithm which is able to infer finite
transducers with bounded lookahead. Our transducer learning
algorithms can also be easily extended in the symbolic setting
by expanding our SFA algorithm.

Equivalence Query Implementation: We present the Gram-
mar Oriented Filter Auditing (GOFA) algorithm which imple-
ments an equivalence oracle with a single membership query
for each equivalence query and demonstrate that it is capable
to either detect a vulnerability in the filter if one is present or,
if no vulnerability is present, to recover a good approximation
of the target filter.

Conversion to BEK programs: We present, in appendix C
an algorithm to convert our inferred models of sanitizers into
BEK programs which can then be analyzed using the BEK
infrastructure enabling further applications.

Applications/Evaluation: We showcase the wide applicabil-
ity of our algorithms with a number of applications. Specifically,
we perform a thorough evaluation of our SFA learning al-
gorithm and demonstrate that it achieves a big performance
increase on the total number of queries performed. We also
evaluate our GOFA algorithm and demonstrate that it is able
to either detect attacks when they are present or give a good
approximation of the target filter. To showcase our transducer
learning algorithms we infer models of several HTML en-
coders, convert them to BEK program and check them for
equivalence.

We point out that, due to lack of space all proofs have been
moved into the appendix.

II. Preliminaries

A. Background in Automata Theory

If \( M \) is a deterministic finite automaton (DFA) defined over
alphabet \( \Sigma \), we denote by \(| M |\) the number of states of \( M \) and
by \( \mathcal{L}(M) \) the language that is accepted by \( M \). For any \( k \)
we denote by \([k]\) the set \( \{1, \ldots, k\} \). We denote the set of states
of \( M \) by \( Q_M \). A certain subset \( F \) of \( Q_M \) is identified as the
set of final states. We denote by \( l : Q_M \to \{0, 1\} \) a function
which identifies a state as final or non final. The program of
the finite automaton \( M \) is determined by a transition function
\( \delta \) over \( Q_M \times \Sigma \to Q_M \). For an automaton \( M \) we denote by
\( \neg M \) the automaton \( M \) with the final states inverted.

A push-down automaton (PDA) \( M \) extends a finite au-
tomaton with a stack. The stack accepts symbols over an
alphabet \( \Gamma \). The transition function is able to read the top of the
stack. The transition function is over \( Q_M \times \Sigma \times (\Gamma \cup \{\epsilon\}) \to
Q_M \times (\Gamma \cup \{\epsilon\}) \). A context-free grammar (CFG) \( G \) comprises
a set of rules of the form \( A \to w \) where \( A \in V \) and
\( w \in (\Sigma \cup V)^* \) where \( V \) is a set of non-terminal symbols.
The language defined by a CFG \( G \) is denoted by \( L(G) \).

A transducer \( T \) extends a finite automaton with an output
tape. The automaton is capable of producing output in each
transition that belongs to an alphabet \( \Gamma \). The transition function
is defined over \( Q_M \times (\Sigma \cup \{\epsilon\}) \to Q_M \times (\Gamma \cup \{\epsilon\}) \). A
Mealy Machine \( M \) is a deterministic transducer without \( \epsilon \) transitions
where, in addition, all states are final. A non-
deterministic transducer has a transition function which is a
relation \( \delta \subseteq Q_M \times (\Sigma \cup \{\epsilon\}) \times Q_M \times (\Gamma \cup \{\epsilon\}) \). For
general transducers (deterministic or not), following [8], we extend
the definition of a transducer to produce output over \( \Gamma^* \). A non-
deterministic transducer is single-valued if it holds that for any \( w \in \Sigma^* \) there exists at most one \( \gamma \in \Gamma^* \) such that \( T \) on \( w \) outputs \( \gamma \). A single-valued transducer \( T \) has the
bounded lookahead property if there is a \( k \) such that any sequence of transitions involves at most \( k \) consecutive
non-accepting states. We call such a sequence a lookahead path or lookahead transition. In a single valued transducer
with bounded lookahead we will call the paths that start and
finish in accepting states and involve only non-accepting states
as lookahead paths. The path in its course consumes some
input \( w \in \Sigma^* \) and outputs some \( \gamma \in \Gamma^* \). The bounded
lookahead property definition is based on the one given by
Veanes et al. [14] for Symbolic Transducers, however our
definition better fits our terminology and the intuition behind
our algorithms.

For a given automaton \( M \), we denote by \( M_{\neg s} \) the state
reached when the automaton is executed from state \( q \) on input
\( s \). When the state \( q \) is omitted we assume that \( M \) is executed
from the initial state. Let \( l : Q \to \{0, 1\} \) be a function denoting
whether a state is final. We define the transduction function
\( T_M(u) \) as the output of a transducer/Mealy Machine \( M \) on
input \( u \) omitting the subscript \( M \) when the context is clear.
For transducers we will also use the notation \( u[M]v \) to signify
that \( T_M(u) = v \) for a transducer \( M \).

For a string \( s \), denote by \( s_i \) the \( i \)-th character of the string.
In addition, we denote by \( s_{>i} \), the substring \( s \) starting after \( s_i \).
The operators \( s_{<i}, s_{>i}, s_{\leq i}, s_{\geq i} \) are defined similarly. We denote
by \( \text{suff}(s, k) \) the suffix of \( s \) of length \( k \).

Given two DFA’s \( M_1, M_2 \) it is possible to compute the
intersection \( M = M_1 \cap M_2 \) of the two as follows. The set
of states of \( M \) is the Cartesian product \( Q_1 \times Q_2 \) and the transition
function combines the two individual transition functions to
traverse over the pair of states simultaneously. The accepting
states of \( Q_M \) are those that are simultaneously accepting for
\( M_1, M_2 \). We can use exactly the same algorithm to obtain the
intersection between a DFA \( M_1 \) and a PDA \( M_2 \). The resulting
machine \( M \) is a PDA that inherits the stack operations of \( M_2 \).
Moreover, one can trivially compute the complement of a
DFA by switching all terminal states with non terminal and
vice-versa.

Transducers are not closed under intersection and dif-
fERENCE, and if the transducer is non-deterministic checking
properties as simple as equality is undecidable. However,
in the case the transducer is deterministic or single valued
then equality can be efficiently computed and in the case the
transducers are not equal one can exhibit a string in which the
two transducers are different efficiently [15].

B. Symbolic Finite State Automata

Symbolic Finite Automata (SFA) [16] extend classical
automata by allowing transitions to be labelled with predicates
rather than with concrete alphabet symbols. This allows for
more compact representation of automata with large alphabets
and it could allow automata that are impossible to model as
DFAs when the alphabet size is infinite, as in the case where
Σ = Z. For the following we refer to a set of predicates P as a
predicate family.

Definition 1. (Adapted from [16]) A symbolic finite automaton
or SFA A is a tuple \((Q, q_0, F, P, \Delta)\), where \(Q\) is a finite
set of states, \(q_0 \in Q\) the initial state, \(F \subseteq Q\) is the set of final
states, \(P\) is a predicate family and \(\Delta \subseteq Q \times P \times Q\) is the
move relation.

A move \((p, \phi, q) \in \Delta\) is taken when \(\phi\) is satisfied from the
current symbol \(\alpha\). We will also use an alternative notation for
a move \((p, \phi, q)\) as \(p \xrightarrow{\phi} q\). We denote by guard\((q)\) the set of predicate
guards for the state \(q\), in other words:

\[
\text{guard}(q) := \{ \phi : \exists p \in Q, (q, \phi, p) \in \Delta \}
\]

In this paper we are going to work with deterministic SFAs,
which we define as follows:

Definition 2. A SFA A is deterministic if for all states \(q \in Q\)
and all distinct \(\phi, \phi' \in \text{guard}(q)\) we have that \(\phi \wedge \phi'\)
is unsatisfiable.

Finally, we assume that for any state \(q\) and for any
symbol \(a\) in the alphabet there exists \(\phi \in \text{guard}(q)\) such that
\(\phi(a)\) is true. We call such an SFA complete.

Finally, we define symbolic finite state transducers, the
corresponding symbolic extension of transducers similarly to
SFAs.

Definition 3. (Adapted from [15]) A symbolic finite transducer
or SFT T is a tuple \((Q, q_0, F, P, \Delta, \Gamma(x))\), where \(Q\) is a finite
set of states, \(q_0 \in Q\) the initial state, \(F \subseteq Q\) is the set of final
states, \(P\) is a predicate family, \(\Gamma(x)\) is a set of terms
representing functions over \(\Sigma \rightarrow \Gamma\) and \(\Delta \subseteq Q \times P \times \Gamma(x) \times Q\)
is the move relation.

C. Access and Distinguishing Strings

We will now define two sets of strings over an automaton
that play a very important role in learning algorithms.

Access Strings: For an automaton \(M\) we define the set of
access strings \(A\) as follows: For every state \(q \in Q_M\), there is
a string \(s_q \in A\) such that \(M[s_q] = q\). Given a DFA \(M\), one
can easily construct a minimal set of access strings by using
a depth first search over the graph induced by \(M\).

Distinguishing Strings: We define the set of distinguishing
strings \(D\) for a minimal automaton \(M\) as follows: For any pair
of states \(q_i, q_j \in Q_M\), there exists a string \(d_{i,j} \in D\) such that
exactly one state of \(M \cdot [d_{i,j}]\) and \(M \cdot [d_{i,j}]\) is accepting. A set
of distinguishing strings can be constructed using the Hopcroft
algorithm for automata minimization [17].

The set of Access and Distinguishing strings play a central
role in automata learning since learning algorithms try to
construct these sets by querying the automaton. Once these
sets are constructed then, as we will see, it is straightforward
to reconstruct the automaton.

D. Learning Model

Our algorithms work in a model called exact learning
from membership and equivalence queries [18], which is a
form of active learning where the learning algorithm operates
with oracle access to two types of queries:

- Membership queries: The algorithm is allowed to
submit a string \(s\) and obtain whether \(s \in \mathcal{L}(M)\).

- Equivalence queries: The algorithm is allowed to
submit a hypothesis \(H\) which is a finite automaton
and obtain either a confirmation that \(\mathcal{L}(H) = \mathcal{L}(M)\)

or a string \(z\) that is a counterexample, i.e., a string \(z\)
that belongs to \(\mathcal{L}(H) \triangle \mathcal{L}(M)\).

1We denote by \(\triangle\) the symmetric difference operation.

The goal of the learning algorithm is to obtain an exact
model of the unknown function. Note that, this model extends
naturally to the case of deterministic Mealy machines and
transducers by defining the membership queries to return the
output of the transducer for the input string. We say that an
algorithm gets black box access to an automaton/transducer
when the algorithm is able to query the automaton with an
input of his choice and obtain the result. No other information
is obtained about the structure of the automaton.

III. LEARNING ALGORITHMS

In this section we present two learning algorithms that
form the basis of our constructions, Angluin’s algorithm for
DFA’s [19] as optimized by Rivest and Schapire [20] and the
Shabhaaz-Groz (SG) algorithm for Mealy machines [12].

A. Angluin’s Algorithm

Consider a finite automaton \(M\). Angluin [19] suggested an
algorithm (referred to as \(L^\ast\)) for learning \(M\). The intuition
behind the functionality of Angluin’s algorithm is to construct
the set of access and distinguishing strings given the two
oracles available to it. Intuitively, the set of access strings
will suggest the set of states of the reconstructed automaton.
Furthermore, a transition from a state labeled with access string
\(s\) to a state labelled with access string \(s'\) while consuming a
symbol \(b\) will take place if and only if the string \(sb\) leads to a
state that cannot be distinguished from \(s'\).

In order to reconstruct the set of access and distinguishing
strings the algorithm starts with the known set of access strings
(initially just \(\{\epsilon\}\) ) and, using equivalence queries, expands
the set of access and distinguishing strings until the whole
automaton is reconstructed.
**Technical Description.** The variant $L^*$ we describe below is due to Rivest and Schapire [20]. The main data structure used by the $L^*$ algorithm is the observation table.

**Definition 4.** An observation table $OT$ with respect to an automaton $M$ is a tuple $OT = (S, W, T)$ where

- $S \subseteq \Sigma^*$ is a set of access strings.
- $W \subseteq \Sigma^*$ is a set of distinguishing strings which we will also refer to as experiments.
- $T$ is a partial function $T : \Sigma^* \times \Sigma^* \rightarrow \{0, 1\}$.

The function $T$ maps strings into their respective state label in the target automaton, i.e., $T(s, d) = l(M[s \cdot d])$. We note here that $T$ is defined only for those strings $s, d$ such that $s \cdot d$ was queried using a membership query.

Next we define an equivalence relation between strings with respect to a set of strings and a finite automaton $M$.

**Definition 5. (Nerode Congruence)** Given a finite automaton $M$, for a set $W \subseteq \Sigma^*$ and two strings $s_1, s_2$ we say that

$s_1 \equiv s_2 \text{ mod } W$

when for all $w \in W$ we have that $l(M[s_1 \cdot w]) = l(M[s_2 \cdot w])$.

Note that for any $M$ there will be a finite number of different equivalence classes for any set $W$ (this stems immediately from the fact that $M$ is a finite automaton). This relates to the Myhill-Nerode theorem [21] that, for the above equivalence defined over a language $L$ (i.e., requiring that either both $s_1 \cdot w, s_2 \cdot w \in L$ or none), it states that having a finite number of equivalence classes for $L$ is equivalent to $L$ being regular.

The observation table is going to give us a hypothesis automaton $H$ when the property of closedness holds for the table.

**Definition 6.** Let $OT = (S, W, T)$ be an observation table. We say that $OT$ is closed when, for all $t \in S \cdot \Sigma$, there exists $s \in S$ such that $t \equiv s \text{ mod } W$.

Given a closed observation table we can produce a hypothesis automaton as follows: For each string $s \in S$ we create a state $q_s$. The initial state is $q_\varepsilon$. For a state $q_s$ and a symbol $b \in \Sigma$ we set $\delta(q_s, b) = q_{s \cdot b}$ iff $s \cdot b \equiv t \text{ mod } W$. By the closedness property there will be at least one such string. In the following, we will also see that by the way we fill the table that string will always be unique.

We are now ready to describe the algorithm: Initially we start with the observation table $OT = (S \equiv \{\varepsilon\}, W = \{\varepsilon\}, T)$. The table $T$ has $|\Sigma| + 1$ rows and is filled by querying an equal number of membership queries. The table is checked for closedness. If the table is not closed then let $t \in S \cdot \Sigma$ be a string such that for all $s \in S$, we have that $s \not\equiv t \text{ mod } W$. Then, we set $S = S \cup \{t\}$, complete remaining entries of the table via $|\Sigma|$ membership queries and we check again for closedness. Eventually the table becomes closed and we create a hypothesis automaton $H$. Observe that the number of times we will repeat the above process until we reach a closed table cannot exceed $|Q_M|$. A useful invariant in the above algorithmic process is the property of the observation table $OT$ to be reduced: for all $s, s' \in S$ it holds that $s \not\equiv s' \text{ mod } W$. Observe that the initial OT is trivially reduced while augmenting the set $S$ with a new state as described above preserves the property.

Now suppose that we have a hypothesis automaton $H$ produced by a closed and reduced observation table. Given $H$, the algorithm makes an equivalence query and based on the outcome either the algorithm stops (no counterexample exists) or the counterexample $z$ is processed and the set of distinguishing strings $W$ is augmented by one element as shown below.

**Processing a counterexample.** For any $i \in \{0, \ldots, |z|\}$ define $\alpha_i$ to be the outcome (that is accept or reject) that is produced by processing the first $i$ symbols of $z$ with the hypothesis $H$ and the remaining with $M$ in the following manner. Given $i$ we simulate $H$ on the first $i$ symbols of $z$ to obtain a state $s_i \in S$. Let $z_{>i}$ be the suffix of $z$ that is not processed yet; by submitting the membership query $s_i \cdot z_{>i}$ we obtain $\alpha_i$. Observe that based on the fact that $z$ is a counterexample it holds that $\alpha_0 \neq \alpha_i$. It follows that there exists some $i_0 \in \{0, \ldots, |z| - 1\}$ for which $\alpha_{i_0} \neq \alpha_{i_0+1}$. We can find such $i_0$ via a binary search using $O(|\log |z|)$ membership queries. The new distinguishing string $d$ will be defined as the suffix of $z_{>i_0}$ that excludes the first symbol $b$ (denoted as $z_{>i_0+1}$). We observe the following: recall that $\alpha_{i_0}$ is the outcome of the membership query of $s_{i_0} \cdot z_{>i_0} \equiv s_{i_0} \cdot b \cdot z_{>i_0+1}$ and $\alpha_{i_0+1}$ is the outcome of the membership query $s_{i_0+1} \cdot z_{>i_0+1}$. Furthermore, in $H$, $s_{i_0}$ transitions to $s_{i_0+1}$ by consuming $b$, hence we have that $s_{i_0} \cdot b \equiv s_{i_0+1} \text{ mod } W$. By adding $d = z_{>i_0+1}$ to $W$ we have that $T(s_{i_0} \cdot b, z_{>i_0+1}) \neq T(s_{i_0+1} \cdot z_{>i_0+1})$ and hence the state $s_{i_0+1}$ and the state that is derived by $s_{i_0}$ consuming $b$ should be distinct (while $H$ pronounced them equal). We observe that the new observation table $OT$ is not closed anymore: on the one hand, it holds that $s_{i_0} \cdot b \not\equiv s_{i_0+1} \text{ mod } W \cup \{d\}$ (note that since $\varepsilon \in W$ it should be that $d \not\equiv \varepsilon$), while if $s_{i_0} \cdot b \equiv s_j \text{ mod } W \cup \{d\}$ for some $j \neq i_0 + 1$ this would imply that $s_{i_0} \cdot b \equiv s_j \text{ mod } W$ and thus $s_{i_0+1} \equiv s_j \text{ mod } W$ as well. This latter equality contradicts the property of the $OT$ being reduced. Hence we conclude that the new OT is not closed and the algorithm continues as stated above (specifically it will introduce $s_{i_0} \cdot b$ as a new state in $S$ and so on).

We remark that originally, $L^*$ as described by Angluin added all prefixes of a counterexample in $S$ and thus violated the reduced table invariant (something that lead to a suboptimal number of membership queries). The variant of $L^*$ we describe above due to [20] maintains the reduced invariant.

For a target automaton $M$ with $n$ states, the total number of membership queries required by the algorithm is bounded by $n^2(|\Sigma| + 1) + n \log m$ where $m$ is the length of the longest counterexample.

**B. The Shabazz-Groz (SG) Algorithm**

In [12], Shabazz and Groz extended Angluin’s algorithm to the setting of Mealy machines which are deterministic Transducers without $\varepsilon$-transitions.

The core of the algorithm remains the same: a table $OT$ will be formed and as before will be based on rows corresponding to $S \subseteq S \times \Sigma$ and columns corresponding to distinguishing strings $W$. The table $OT$ will not be a binary
table in this case, but instead it will have values in $\Gamma^*$. Specifically, the partial function $T$ in the SG observation table is defined as $T(s, d) = \text{suffix}(T(sd), |d|)$. The rows of $T$ satisfy the non-equivalence property, i.e., for any $s, s' \in S$ it holds that $s \not\equiv s'$ mod $W$, thus as in the Rivest-Schapire variant of $L^*$ each access string corresponds to a unique state in the hypothesis automaton. Further, provided that $\Sigma \subseteq W$, we have for each $s \in S$, the availability of the output symbol produced when consuming any $b \in \Sigma$ is given by $T(s, b)$. In this way a hypothesis Mealy machine can be constructed in the same way as in the $L^*$ algorithm. On the other hand, Shabbz and Groz [12] contribute a new method for processing counterexamples described below.

Let $z$ be a counterexample, i.e., it holds that the hypothesis machine $H$ and the target machine produce a different output in $\Gamma$. Let $s$ be the longest prefix of $z$ that belongs to the access strings $S$. If $s \cdot d = z$, in [12] it is observed that they can add $d$ as well as all of its suffixes as columns in $OT$. The idea is that at least one of the suffixes of $d$ will contain a distinguishing string and thus it can be used to make the table not closed. In addition, this method of processing counterexamples makes the set $W$ suffix closed. After adding all suffixes and making the corresponding membership queries, the algorithm proceeds like the $L^*$ algorithm by checking the table for closedness. The overall query complexity of the algorithm is bounded by $O(|\Sigma|^2 n + |\Sigma|mn^2)$ queries, where $n, m, \Sigma$ are defined as in the $L^*$ algorithm.

IV. LEARNING SYMBOLIC AUTOMATA

In this section we present our algorithm for learning symbolic finite automata for general predicate families. Then, we specialize our algorithm for the case of regular expression filters.

A. Main Algorithm

Symbolic finite automata extend classical finite automata by allowing transitions to be labelled by predicate formulas instead of single symbols. In this section we will describe the first, to the best of our knowledge, algorithm to infer SFA's from membership and equivalence queries. Our algorithm, contrary to previous efforts to infer symbolic automata [22] which required the counterexample to be of minimal length, works in the standard membership and equivalence query model under a natural assumption, that the guards themselves can be inferred using queries.

The main challenge in learning SFA’s is that counterexamples may occur due to two distinct reasons: (i) a yet unlearned state in the target automaton (which is the only case in the $L^*$ algorithm), (ii) a learned state with one of the guards being incorrect and thus, leading to a wrong transition into another already discovered state. Our main insight is that it is possible to distinguish between these two cases and suitably adjust either the guard or expand the hypothesis automaton with a new state.

Technical Description. The algorithm is parameterized by a predicate family $P$ over $\Sigma$. The goal of the algorithm is to both infer the structure of the automaton and label each transition with the correct guard $\phi \in P$. Compared to the $L^*$ algorithm, our learning algorithm, on top of the ability to make membership and equivalence queries will also require that the guards come from a predicate family for which there exists a guard generator algorithm that we define below.

**Definition 7.** A guard generator algorithm $\text{guardgen}()$ for a predicate family $P$ over an alphabet $\Sigma$ takes as input a sequence $R$ of pairs $(b, q)$ where $b \in \Sigma$ and $q$ an arbitrary label and returns a set of pairs $G$ of the form $(\phi, q)$ such that the following hold true:

- (Completeness) $\forall(b, q) \in R \exists \phi : (\phi, q) \in G \land \phi(b)$.
- (Uniqueness) $\forall\phi, \phi', q : (\phi, q), (\phi', q) \in G \rightarrow \phi = \phi'$.
- (Determinism) $\forall b \in \Sigma \exists (\phi, q) \in G : \phi(b)$.

The algorithm fails if such set of pairs does not exist.

Given a predicate family $P$ that is equipped with a guard generator algorithm, our SFA learning algorithm employs a special structure observation table $SOT = (S, W, \Lambda, T)$ so that the table $T$ has labelled rows for each string in $\Sigma \cup \Lambda$ where $\Lambda \subseteq S \cdot \Sigma$. The initial table is $SOT = \{S = \{\varepsilon\}, W = \{\varepsilon\}, \Lambda = \emptyset, T\}$. Closedness of $SOT$ is determined by checking that for all $s \in S$ it holds that $sb \in \Lambda \implies bs' \in S : (sb \equiv s' \mod W)$. Furthermore the table is reduced if and only if for all $s, s' \in S$ it holds that $s \not\equiv s' \mod W$. Observe that the initial table is (trivially) closed and reduced.

Our algorithm operates as follows. At any given step, it will check $T$ for closedness. If a table is not closed, i.e., there is a $sb \in \Lambda$ such that $sb \not\equiv s'$ for any $s' \in S$, the algorithm will add $sb$ to the set of access strings $S$ updating the table accordingly.

On the other hand, if the table is closed, a hypothesis SFA $H = (Q_H, q_0, F, P, \Delta)$ will be formed in the following way. For each $s \in S$ we define a state $q_s \in Q_H$. The initial state is $q_{\varepsilon}$. A state $q_s$ is final iff $T(s, \varepsilon) = 1$. Next, we need to determine the move relation that contains triples of the form $(\phi, q', q)$ with $\phi \in P$. The information provided by $SOT$ for each $q_s$ is the transitions determined by the rows $T(sb)$ for which it holds $sb \in \Lambda$. Using this we form the pairs $(b, q_{s'})$ such that $sb \equiv s' \mod W$ (the existence of $s'$ is guaranteed by the closedness property). We then feed those pairs to the $\text{guardgen}()$ algorithm that returns a set $G_{q_s}$ of pairs of the form $(\phi, q)$. We set $\text{guard}(q_s) = \{\phi : (\phi, q) \in G_{q_s}\}$ and add the triple $(q_s, \phi, q)$ in $\Delta$. Observe that by definition the above process when executed on the initial $SOT$ returns as the hypothesis SFA a single state automaton with a self-loop marked with $\text{true}$ as the single transition over the single state.

**Processing Counterexamples.** Assume now that we have a hypothesis SFA $H$ which we submit to the equivalence oracle. In case $H$ is correct we are done. Otherwise, we obtain a counterexample string $z$. First, as in the $L^*$ algorithm, we perform a binary search that will identify some $i_0 \in \{0, 1, \ldots, |z| - 1\}$ for which the response of the target machine is different for the strings $s_{i_0}z_{>i_0}$ and $s_{i_0+1}z_{>i_0+1}$. This determines a new distinguishing string defined as $d = z_{>i_0+1}$.

Notice that $s_{i_0}b \not\equiv s_{i_0+1} \mod W \cup \{d\}$ something that reflects that $s_{i_0}$ over $b$ should not transition to $s_{i_0+1}$ as the hypothesis has predicted. In case $s_{i_0}b \not\equiv s_{i_0+1} \mod W \cup \{d\}$ for any $j$, the table will become not closed if augmented by $d$ and thus the algorithm will proceed by adding $d$ to $W$ and update
the table accordingly (this is the only case that occurs in
the \( L^* \) algorithm). On the other hand, it may be the case
that adding \( d \) to \( SOT \) preserves closedness as it may be that
\( s_i, b, s_j \equiv s_j \mod W \cup \{d\} \) for some \( j \neq i_0 + 1 \). This
does not contradict the fact that the table prior to its augmentation
was reduced, as in the case of the \( L^* \) algorithm, since the
transition \( s_{i_0} \) to \( s_{i_0+1} \) when consuming \( b \) that is present in
the hypothesis could have been the product of \( \text{guardgen}(R) \)
and not an explicit transition defined in \( \Lambda \). In such case \( \Lambda \)
is augmented with \( s_i, b, s_j \) and the algorithm will issue another
equivalence query, continuing in this fashion until the \( SOT \)
becomes not closed or the hypothesis is correct.

The above state of affairs distinguishes our symbolic learn-
ing algorithm from learning via the \( L^* \) algorithm: not every
equivalence query leads to the introduction of a new state.
We observe though that some progress is still being made:
if a new state is not discovered by an equivalence query, the
set \( \Lambda \) will be augmented making a transition that was before
implicit (defined via a predicate) now explicit. For suitable
predicate families this augmentation will lead to more refined
guard predicates which in turn will result to better hypothesis
SFA's submitted to the equivalence oracle and ultimately to
the reconstruction of an SFA for the target.

In order to establish formally the above we need to prove
that the algorithm will converge to a correct SFA in a finite
number of steps (note that the alphabet \( \Sigma \) may be infinite
for a given target SFA and thus the expansion of \( \Lambda \) by each
equivalence query is insufficient by itself to establish that the
algorithm terminates).

Convergence can be shown for various combinations of
predicate families \( P \) and \( \text{guardgen}(\cdot) \) algorithms that relate to
the ability of the \( \text{guardgen}(\cdot) \) algorithm to learn guard predi-
cates from the family \( P \). One such case is when \( \text{guardgen}(\cdot) \)
learns predicates from \( P \) via counterexamples. Let \( G \subset 2^P \)
a guard predicate family. Intuitively, the \( \text{guardgen}(\cdot) \) algorithm
operates on a training set containing actual transitions from
a state that were previously discovered. Given the symbols
labeling those transitions, the algorithm produces a candidate
guard set for that state. If the training set is small the candidate
guard set is bound to be wrong and a counterexample will
exist. The \( \text{guardgen}(\cdot) \) algorithm learns the guard set via
counterexamples if by adding a counterexample in the training
set in each iteration the set is augmented with a
counterexample from the previous guard set.

We are now ready to prove the correctness of our SFA
learning algorithm.

Theorem 1. Consider a guard predicate family \( G \) that is t-
learnable via counterexamples using a \( \text{guardgen}(\cdot) \) algorithm.
The class of deterministic symbolic finite state automata with
guards from \( G \) can be learned in the membership and equiva-
ence query model using at most \( O(n^{(\log m + n)l(k)}) \) queries,
where \( n \) is size of the minimal SFA for the target language,
\( m \) is the maximum length of a counterexample, and \( k \) is the
maximum outdegree of any state in the minimal SFA of the
target language.

In appendix D we describe an example of a \( \text{guardgen}(\cdot) \)
algorithm when SFAs are used to model decision trees.

B. A Learning Algorithm for RE Filters

Consider the SFA depicted in figure 1 for the regular
expression \((a+b)^*\). This represents a typical regular ex-
pression filter automaton where a specific malicious string is
matched and at that point any string containing that malicious
substring is accepted and labeled as malicious. When testing
regular expression filters many times we would have to test
different character encodings. Thus, if we assume that the
alphabet \( \Sigma \) is the set of two byte character sequences as
it would be in UTF-16, then each state would have to test
16 different transitions, making traditional learning algorithms too
inefficient, while we point out that the full unicode standard
contains around 110000 characters.

We will now describe a guard generator algorithm and
demonstrate that it efficiently learns predicates resulting from
regular expressions. The predicate family used by our algo-

1

"We use the notation \( |\phi| = |\{b | \phi(b) = 1\}|.\)
we will replace membership queries with transduction queries. In the learning algorithms of this section, to deobfuscate the input before passing it through regular by mod-security, a popular web application firewall, in order finally, the third sanitizer is a transformation function used with a Mealy machine which requires that only one output but allow to assume that the resulting Mealy machine is deterministic. This transformation is not expressible with a \( \emptyset \)-transitions. This transformation is not expressible, cf. Figure 5.

A. Improved learning of Mealy machines

In this section we describe two improvements of the SG algorithm for Mealy machines. In the first one we provide an efficiency improvement over SG on the number of transduction queries required in order to learn a target Mealy machine of size \( n \). Specifically we drop the counterexample processing complexity from \( O(m \cdot n) \) to \( O(m + \log n) \) where \( m \) is the length of the counterexample. Our main observation is that contrary to what is implied by Shabaz and Groz, processing Mealy machine counterexamples can take advantage of the binary-search counter example processing similar to Rivest-Schapire’s version of the \( L^* \) algorithm something that leads to major improvements in the query complexity of the algorithm. In our second improvement we show how the learning algorithm can handle a more general class of Mealy Machines which are deterministic but also allow \( \varepsilon \)-transitions in the input. In practice, this modification allows for multiple symbols in the output to be produced for each single input symbol. This case is particularly relevant to our setting as such Mealy machines are very frequently encountered in practice notably as string encoders such as url and HTML encoders, cf. Figure 5.

**Improved Counterexample Processing:** We now introduce a new way of handling counterexamples in the SG algorithm that is based on Rivest and Schapire’s version of the \( L^* \) algorithm [20]. Recall that in the SG algorithm all the suffixes of a counterexample are added as new experiments in the table and therefore, in the worst case, \( O(m \cdot n) \) new entries must be filled in the table using transduction queries where \( m \) is the length of the counterexample and \( n \) is the number of access strings.

Our improved counterexample processing operates as follows. Suppose that \( z \) is the given counterexample, i.e. it is a string where the target machine and the hypothesis disagree. Furthermore suppose that the hypothesis transducer is produced by a reduced observation table. We notice that even though the last state reached in the counterexample may be identical in both cases, we can find a point where a wrong state is traversed by the counterexample by inspecting the transduction of \( z \). Indeed, there exists a (smallest) index \( i \) such that \( T_H(z)_i \neq T_M(z)_i \). Therefore we can conclude that \( z_{<i} \) reaches different states in the hypothesis and target machine. It follows we can trim the counterexample to \( z' = z_{\leq i} \) and this way we know that the last symbol produced by the counterexample is wrong in the hypothesis automaton.

We now describe formally our improved counterexample processing algorithm. For any \( j \in \{0,\ldots,|z'|\} \) let \( \gamma_j \) be a string that is produced as follows: first run the hypothesis \( H \) machine on \( z'_{\leq j} \) to obtain \( z'_{<j} \); the hypothesis terminates on a state \( s_j \); subsequently submit \( s_j, z'_{<j} \) to \( M \) in order to obtain a string \( \gamma_j \). Let \( \gamma_j = \gamma_j^H \text{ suff}(\gamma_j^M, |z'_{<j} - j) \) and observe that \( \gamma_0 = T_M(z') \), \( \gamma_{|z'|} = T_H(z') \) and \( \gamma_0 \neq \gamma_{|z'|} \).

The binary search then is performed in this fashion. The initial range is \( [0,|z'|] \) and the midpoint is \( j = \lceil |z'|/2 \rceil \). Given a range \([j_{\text{left}}, j_{\text{right}}]\) and a middle point position \( j \), we check whether \( \gamma_j = \gamma_0 \); if this is the case we set the new range as \([j_{\text{right}}, j_{\text{left}} - 1]\) and we continue recursively. The process finishes when the range is a singleton \([j_{0}, j_{0}]\) which is the output of the search.
\( x \in [A-Z]/x - 32 \)

Fig. 2. ToLowerCase function. Mealy machine.

\( x \notin [A-Z]/x \)

Fig. 3. Simplified version of HTML Encoder function. Deterministic Transducer with multiple output symbols per transition.

\[ x = <[/ \&, \ l, \ t, \ ; ] \]

Fig. 4. ReplaceComments Mod-security transformation function. Non deterministic Transducer with \( \epsilon \) transitions and 1-lookahead.

Fig. 5. Three different sanitizers implementing widely used functions and their respective features when modeled as transducers. Only the first sanitizer can be inferred using existing algorithms.

**Theorem 2.** The binary search process described above returns \( j_0 \in \{0, \ldots, |z'| - 1 \} \) such that \( \gamma_{j_0} \neq \gamma_{j_0+1} \).

Given such \( j_0 \), we observe that since the prefixes of \( \gamma_{j_0}, \gamma_{j_0+1} \) that correspond to the processing of \( z_{\leq j_0} \) are identical by definition, the difference between the strings should lie in their suffixes. Furthermore, \( (\gamma_{j_0}, j_0+1)T_M(sd) \) since the former is the last output symbol produced by \( H \) when consuming \( z_{\leq j_0}b \) and the latter is the last symbol produced by \( M \) when consuming \( s_{j_0}b \), where \( b = z'_{j_0+1} \) is the \( (j_0+1) \)-th symbol of the counterexample. As a result the difference of \( \gamma_{j_0}, \gamma_{j_0+1} \) is in their \( (|z'|-j_0-1) \)-suffixes that by definition are equal to the same length suffixes of \( \gamma_{j_0}, \gamma_{j_0+1} \). This implies that \( j_0 < |z'| - 1 \) and thus we can define a new distinguishing string \( d = z'_{1:j_0+1} \). The observation table augmented by this new string \( d \) is not closed anymore: the string \( s_{j_0}bd = s_{j_0}z'_{1:j_0} \) when queried to \( M \) produces the string \( \gamma_{j_0}M \) which disagrees in its \( |d| \)-suffix with the string \( \gamma_{j_0+1}M \) produced by \( M \) on input \( s_{j_0+1}d \). Closing the table will now introduce the new access string \( s_{j_0}b \) and hence the algorithm continues by expanding the hypothesis machine.

The approach we outlined above offers a significant efficiency improvement over the SG algorithm. Performing the binary search detailed above requires merely \( O(\log m) \) queries where \( m \) is the length of the counterexample. This gives a total of \( O(n + \log m) \) queries for processing a counterexample as opposed to the \( O(n \cdot m) \) of the SG algorithm where \( n \) is the number of access strings in the observation table.

**Handling \( \epsilon \)-transitions:** We next show how to tackle the problem of a Mealy machine that takes \( \epsilon \)-transitions but still is deterministic in its output. The effect of such \( \epsilon \)-transitions is that many or no output symbols may be generated due to a single input symbol. Even though this is a small generalization it complicates the learning process. First, if more than one output symbols are produced for each input symbol our counterexample processing method will fail because the breakpoint output symbol \( (T_M(z)) \) may be produced by less than \( i \) symbols of \( z \). Further, in the observation table, bookkeeping will be inaccurate since, if we keep only the suffix \( T_M(sd), |d| \) string in each table entry, then this might not correspond to the output symbols that correspond to last \( d \) symbols of the input string.

We show next how to suitably modify our bookkeeping and counterexample processing so that Mealy machines with \( \epsilon \)-transitions are handled.

Instead of keeping in each table entry the string \( \text{suffix} (T_M(sd), |d|) \) we only keep the output that corresponds to the experiment \( d \). While in standard Mealy machines this is simply \( \text{suffix}(T_M(sd), |d|) \), when \( \epsilon \)-transitions are used the output may be longer or shorter. Therefore, we compute the output of the experiment as the substring of \( T_M(sd) \) when we subtract the longest common prefix with the string \( T_M(s) \). Intuitively, we keep only the part of the output that is produced by the experiment \( d \). Given that we do not know the length of that output we subtract the output produced by the access string \( s \). Notice that, because the observation table is prefix closed, we can obtain the output \( T_M(s) \) without making an additional transduction query to the target \( M \).

When processing a counterexample, the method we outlined above can still be used. However, as we mentioned, the index \( i \) where the output of the hypothesis and the target machine differ may not be the correct index in which we must trim the input at. Specifically, if \( T_H(z) \) and \( T_M(z) \) differ in position \( i \) (and \( i \) is the smallest such position), then we are looking for an index \( i' \leq i \) such that \( T_M(z < i') = T_M(z)_{\leq i} \). Given \( i \), such a position \( i' \) can be found with \( \log |z| \) queries using a binary search on the length of the output of each substring of \( z \). We will then define \( z' = z_{\leq i'} \).

Given the above modifications we will seek \( j_0 \) via a binary search as in Theorem 2 but using the strings \( \gamma_j \) that are defined as \( \gamma_jH \cdot \text{suffix}(\gamma_jM, |\gamma_jM| - j') \) where \( j' = |T_M(s_j)| \) for \( j = 0, \ldots, |z'| \). Then, the same proof as in Theorem 2 applies. Further, using a similar logic as before we argue that the string \( d = z_{1:j_0+1} \) is non-empty and it can be used as a new distinguishing string. The asymptotic complexity of the algorithm will remain the same.

**B. Learning Transducers with Bounded Lookahead**

It is easy to see that if the target machine is a single-valued non-deterministic transducer with the bounded lookahead property the algorithm of the previous section fails. In fact the algorithm may not even perform any progress beyond the initial single state hypothesis even if the number of states of the target is unbounded; for instance, consider a transducer that modifies only a certain input symbol sequence \( u \) (say by redacting its first symbol) while leaving the remaining input intact. The algorithm of the previous section will form a
hypothesis that models the identity function and obtain from the equivalence oracle, say, the string \( w \) as the counterexample (any string containing \( w \) would be a counterexample, but \( w \) is the shortest one). The binary search process will identify \( j_0 = 0 \) (it is the only possibility) and will lead the algorithm to the adoption of \( d = w_{>1} \) as the distinguishing string. However, \( T_M(s_{j_0}, bd) = T_M(w) = w_{>1} \) and also \( T_M(s_{j_0+1d}) = w_{>1} \) hence \( d \) is not distinguishing: \( s_{j_0} b \equiv s_{j_0+1} \mod W \cup \{d\} \). At this moment the algorithm is stuck: the table remains closed and no progress can be made. For the following we assume that the domain of the target transducer is \( \Sigma^* \), i.e. for every string \( \alpha \in \Sigma^* \) there exists exactly one \( \gamma \in \Gamma^* \) such that \( T_M(\gamma) = \gamma \).

Technical Description. The algorithm we present builds on our algorithm in the previous section for Mealy Machines with \( \varepsilon \)-transitions. Our algorithm views the single-valued transducer as a Mealy Machine with \( \varepsilon \)-transitions augmented with certain lookahead paths. As in the previous section we use an observation table \( OT \) that has rows on \( S \cup S \times \Sigma \) and columns corresponding to the distinguishing strings \( W \). In addition our algorithm holds a lookahead list \( L \) of quadruples \((src, dst, \alpha, \gamma)\) where \( src, dst, \alpha, \gamma \) are index numbers of rows in the \( OT \), \( \alpha \in \Sigma^* \) is the input string consumed by the lookahead path, while \( \gamma \in \Gamma^* \) is the output produced by the lookahead path. Whenever a lookahead path is detected, it is added in the lookahead transition list \( L \). Our algorithm will also utilize the concept of a prefix-closed membership query: In a prefix closed membership query, the input is a string \( s \) and the result is the set of membership queries for all the prefixes of \( s \). Thus, if \( O \) is the membership oracle, then a prefix-closed membership query on input a string \( s \) will return \( \{O(s_{\leq 1}), \ldots, O(s)\} \). We will now describe the necessary modifications in order to detect and process lookahead transitions.

Detecting and Processing lookahead transitions. Observe that in a deterministic transducer the result of a prefix-closed query on a string \( s \) would be a prefix closed set \( r_1, \ldots, r_t \). The existence of \( i_0 \in \{1, \ldots, t\} \) with \( r_{i_0} \) not a strict prefix of \( r_{i_0+1} \) suggests that a lookahead transition was followed. Let \( s_{j_0} \) be the longest common prefix of \( r_1, \ldots, r_{i_0+1} \). The state \( src = s_{j_0} \) that corresponds to \( q_{j_0} \) is the state that the lookahead path commences while the state \( dst = s_{i_0+1} \) that corresponds to input \( q_{i_0+1} \) is the state the path terminates. The path consumes the string \( \alpha \) that is determined by the suffix of \( q_{i_0+1} \) starting at the \((j_0 + 1)\)-position. The output of the path is \( \gamma = \text{suff}(r_{i_0+1}|r_{i_0+1}| - |r_{j_0}|) \).

The algorithm proceeds like the algorithm for Mealy machines with \( \varepsilon \)-transitions. However, all membership queries are replaced with prefix-closed membership queries. Every query is checked for a lookahead transition. In case a lookahead transition is found, it is checked if it is already in the list \( L \). In the opposite case the quadruple \((src, dst, \alpha, \gamma)\) is added in \( L \) and all suffixes of \( \alpha \) are added as columns in the observation table. The reason for the last step is that every lookahead path of length \( m \) defines \( m - 2 \) final states in the single-valued transducer. The suffixes of \( \alpha \) can be used to distinguish these states. Finally, when the table is closed, a hypothesis is generated as before taking care to add the respective lookahead transitions, removing any other transitions which would break the single-valuedness of the transducer.

Processing Counterexamples. For simplicity, in this algorithm we utilize the Shabaz-Groz counterexample processing method. We leave the adjustment of our previous binary search counterexample method as future work. Notice that, a counterexample may occur either due to a hidden state or due to a yet undiscovered lookahead transition. We process a counterexample string as follows: We follow the counterexample processing method of Shabaz Groz and we add all the suffixes of the counterexample string as columns in the \( OT \). Since the SG method already adds all suffixes, this also covers our lookahead path processing. In case we detect a lookahead we also take care to add the respective transition in the lookahead list \( L \). Notice that, following the same argument as in the analysis of the SG algorithm, one of the suffixes will be distinguishing, thus the table will become not closed and progress will be made.

Regarding the correctness and complexity of our algorithm we prove the following theorem.

**Theorem 3.** The class of non-deterministic single-valued transducers with the bounded lookahead property and domain \( \Sigma^* \) can be learned in the membership and equivalence query model using at most \( \mathcal{O}(\mid \Sigma \mid n(mn + |\Sigma| + kn)(n + \max(m, n))) \) membership queries and at most \( n + k \) equivalence queries where \( m \) is the length of the longest counterexample, \( n \) is the number of states and \( k \) is the number of lookahead paths in the target transducer.

C. Learning Symbolic Finite Transducers

The algorithm for inferring SFAs can be extended naturally in order to infer SFTs. Due to space constraints we won’t describe the full algorithm here rather sketch certain aspects of the algorithm.

The main difference between the SFA algorithm and the SFT algorithm is that on top of inferring predicates guards, the learning algorithm for SFTs need to also infer the term functions that are used to generate the output of each transition. This implies that there might be more than one transition from a state \( s_i \) to a state \( s_j \) due to differences in the term functions of each transition. This scenario never occurs in the case of SFAs. Thus, the \texttt{guardgen()} algorithm on an SFT inference algorithm should also employ a \texttt{termgen()} algorithm which will work as a submodule of \texttt{guardgen()} in order to generate the term functions for each transition and possibly split a predicate guard into more.

Finally, we point out that in our implementation we utilized a simple SFT learning algorithm which is a direct extension of our RE filter learning algorithm in the sense that we generalize the pair (predicate, term) with the most members to become the sink transition for each state.

VI. IMPLEMENTING AN EQUIVALENCE ORACLE

In practice a membership oracle is usually easy to obtain as the only requirement is to be able to query the target filter or sanitizer and inspect the output. However, simulating an equivalence oracle is not trivial. A straightforward approach is to perform random testing in order to find a counterexample and declare the machines equal if a counterexample is not found after a number of queries. Although this is a feasible approach, it requires a very large number of membership queries.
Taking advantage of our setting, in this section we will introduce an alternative approach where an equivalence oracle is implemented using just a single membership query. To illustrate our method consider a scenario where an auditor is remotely testing a filter or a sanitizer. For that purpose the auditor is in possession of a set of attack strings given as a context free grammar (CFG).

The goal of the auditor is to either find an attack-string bypassing the filter or declare that no such string exists and obtain a model of the filter for further analysis. In the latter case, the auditor may work in a whitebox fashion and find new attack-strings bypassing the inferred filter, which can be used to either obtain a counterexample and further refine the model of the filter or actually produce an attack. Since performing whitebox testing on a filter is much easier than black-box, even if no attack is found the auditor has obtained information on the structure of the filter.

Formally, we define the problem of Grammar Oriented Filter Auditing as follows:

**Definition 9.** In the grammar oriented filter auditing problem (GOFA), the input is a context free grammar $G$ and a membership oracle for a target DFA $F$. The goal is to find $s \in G$, such that $s \notin F$ or determine that no such $s$ exists.

One can easily prove that in the general case the GOFA problem requires an exponential number of queries. Simply consider the CFG $L(G) = \Sigma^*$ and a DFA $F$ such that $L(F) = \Sigma^* \setminus \{\text{random-large-string}\}$. Then, the problem reduces in guessing a random string which requires an exponential number of queries in the worst case. A formal proof of a similar result was presented by Peled et al. [23].

Our algorithm for the GOFA problem uses a learning algorithm for SFAs utilizing Algorithm 1 as an equivalence oracle. The algorithm takes as input a hypothesis machine $H$. It then finds a string $s \in L(G)$ such that $s \notin L(H)$. If the string $s$ is an attack against the target filter, the algorithm outputs the attack-string and terminates. If it is not it returns the string as a counterexample. On the other hand if there is no string bypassing the hypothesis, the algorithm terminates accepting the hypothesis automaton $H$. Note that, this is the point where we trade completeness for efficiency since, even though $L(G \cap \neg H) = \emptyset$, this does not imply that $L(G \cap \neg F) = \emptyset$.

**Algorithm 1 GOFA Algorithm**

```plaintext
function EQUIVALENCE ORACLE(H)
    $G_A \leftarrow G \cap \neg H$
    if $L(G_A) = \emptyset$ then
        return Done
    else
        $s \leftarrow L(G_A)$
        if $O(s) = \text{True}$ then
            return Counterexample, $s$
        else
            return Attack, $s$
        end if
    end if
end function
```

**TABLE 1.** SFA vs. DFA Learning

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<td>9.43</td>
</tr>
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Adaptation to sanitizers. The technique above can be generalized easily to sanitizers. Assume that we are given a grammar $G$ as before and a target transducer $T$ implementing a sanitization function. In this variant of the problem we would like to find a string $s_A$ such that there exists $s \in L(G)$ for which $s_A[T](s)$ holds.

In order to determine whether such a string exists, we first construct a pushdown transducer $T_G$ with the following property: A string $s$ will reach a final state in $T_G$ if and only if $s \in L(G)$. Moreover, every transition in $T_G$ is the identity function, i.e. outputs the character consumed. Therefore, we have a transducer which will generate only the strings in $L(G)$. Finally, given a hypothesis transducer $H$, we compute the pushdown transducer $H \circ T_G$ and check the resulting transducer for emptiness. If the transducer is not empty we can obtain a string $s_A$ such that $s_A[H \circ T_G](s)$. Since $T_G$ will generate only strings from $L(G)$ it follows that $s_A$ when passed through the sanitizer will result in a string $s \in L(G)$. Afterwards, the GOFA algorithm continues as in the DFA case.

In appendix A, B we describe a comparison of the GOFA algorithm with random testing as well as ways in which an complete equivalence oracle may be implemented.

### VII. Evaluation

#### A. Implementation

We have implemented all the algorithms described in the previous sections. In order to evaluate our DFA/SFA learning algorithms in the standard membership/equivalence query model we implemented an equivalence oracle by computing

![Fig. 6. Speedup of SFA vs. DFA learning.](image-url)
In this section we evaluate the efficiency of our GOFA algorithm. In our evaluation we used both the DFA and the SFA algorithms. Since our SFA algorithm uses significantly more equivalence queries than the \( L^* \) algorithm, we need to evaluate whether this additional queries would influence the accuracy of the GOFA algorithm. Specifically, we would like to answer the following questions:

1) How good is the model inferred by the GOFA algorithm when no attack string exists in the input CFG?

2) Is the GOFA algorithm able to detect a vulnerability in the target filter if one exists in the input CFG?

Making an objective evaluation on the effectiveness of the GOFA algorithm in these two questions is tricky due to the fact that the performance of the algorithm depends largely on the input grammar provided by the user. If the grammar is too expressive then a bypass will be trivially found. On the other hand if no bypass exists and moreover, the grammar represents a very small set of strings, then the algorithm is condemned to make a very inaccurate model of the target filter. Next, we tackle the problem of evaluating the two questions about the algorithm separately.

### C. Evaluation of DFA/SFA Learning algorithms

We first evaluate the performance of our SFA learning algorithm using the \( L^* \) algorithm as the baseline. We implemented the algorithms as we described them in the paper using only an additional optimization both in the DFA and SFA case: we cached each query result both for membership and equivalence queries. Therefore, whenever we count a new query we verify that this query wasn’t asked before. In the case of equivalence queries, we check that the automaton complies with all the previous counterexamples before issuing a new equivalence query.

In table I we present numerical results from our experiments that reveal a significant advantage for our SFA learning over DFA: it is approximately 15 times faster on the average. The speedup as the ratio between the DFA and the SFA number of queries is shown in Figure 6. An interesting observation here is that the speedup does not seem to be a simple function of the size of the automaton and it possibly depends on many aspects of the automaton. An important aspect is the size of the sink transition in each state of the SFA. Since our algorithm learns lazily the transitions, if the SFA incorporates many transitions with large size, then the speedup will be less than what it would be in SFAs were the sink transition is the only one with big size.

### D. Evaluation of GOFA algorithm

In this section we evaluate the efficiency of our GOFA algorithm. In our evaluation we used both the DFA and the SFA algorithms. Since our SFA algorithm uses significantly more equivalence queries than the \( L^* \) algorithm, we need to evaluate whether this additional queries would influence the accuracy of the GOFA algorithm. Specifically, we would like to answer the following questions:

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Making an objective evaluation on the effectiveness of the GOFA algorithm in these two questions is tricky due to the fact that the performance of the algorithm depends largely on the input grammar provided by the user. If the grammar is too expressive then a bypass will be trivially found. On the other hand if no bypass exists and moreover, the grammar represents a very small set of strings, then the algorithm is condemned to make a very inaccurate model of the target filter. Next, we tackle the problem of evaluating the two questions about the algorithm separately.
**DFA model generation evaluation.** Intuitively, the GOFA algorithm is efficient in recovering a model for the target filter if the algorithm is in possession of the necessary information in order to recover the filter in the input CFG and is able to do so. Therefore, in order to evaluate experimentally the accuracy of our algorithm in producing a correct model for the target filter independently of the choice of the grammar we used as input grammar the target filter itself. This choice is justified as setting as input grammar the target filter itself we have that a grammar that, intuitively, is a maximal set without any vulnerability.

In table II we present the numerical results of our experiments over the same set of filters used in the experiments of Section VII-C. The learning percentage of both DFA and SFA with simulated equivalence oracle via GOFA is quite high (close to 90% for both cases). The performance benefit from our SFA learning is even more dramatic in this case reaching an average of \( \approx 35 \) times faster than DFA. The speedup is also pictorially presented in Figure 7. We also point out the even though the DFA algorithm checks all transitions of the automaton explicitly (which is the main source of overhead), the loss in accuracy between the \( L^* \) algorithm and our SFA algorithm is only 2\%, for a speedup gain of approximately x35.

**Vulnerability detection evaluation.** In evaluating the vulnerability detection capabilities of our GOFA algorithm we ran into the same problem as with the model generation evaluation; namely, the efficiency of the algorithm depends largely on the input grammar given by the user. If the grammar is more expressive than the targeted filter then a bypass can be trivially found. On the other hand if it is too restrictive maybe no bypass will exist at all.

For our evaluation we targeted SQL Injection vulnerabilities. In our first experiment we utilized five well known web application firewalls and used as an input grammar an SQL grammar from the yaxx project [29]. In this experiment the input filter was running on live firewall installations rather than on the extracted rules. We checked whether there were valid SQL statements that one could pass through the web application firewalls.

The results of this experiment can be found in table IV. We found that in all cases a user can craft a valid SQL statement that will bypass the rules of all five firewalls. For the first 4 products where more complex rules are used the simple statement “open a” is not flagged as malicious. This statement allows the execution of statements saved in the database system before using a “DECLARE CURSOR” statement. Thus, these attacks could be part of an attack which reexecutes a statement already in the database in a return oriented programming manner.

The open statement was flagged malicious by urlscan, in which case GOFA sucessfully detected that and found an alternative vector, “replace”. We also notice, that using GOFA with the SFA learning algorithm makes a minimum number of queries since our SFA algorithm adds new edges to the automaton only lazily to update the previous models, thus making GOFA a compelling option to use in practice.

In the second experiment we performed we tested what will happen if we have a much more constrained grammar against the composition of two rules targetting SQL Injection attacks from PHPIDS. In order to achieve that we started with a small grammar which contains the combination of some attack vectors and, whenever a vector is identified bypassing the filter, we remove the vector from the grammar and rerun it with a smaller grammar until no attack is possible. Here we would like to find out whether the GOFA algorithm can operate under restricted grammars that require many updates on the hypothesis automaton. The successive vectors we used as input grammar can be found in full version of the paper. The results of the experiment can be found in table IV. To check whether a vulnerability exists in the filter we computed the symmetric difference between the input grammar and the targeted filters. We note that this step is the reason we did not perform the same experiment on live WAF installations, since we do not have the full specification as a regular expression and thus cannot check if a bypass exists in an attack grammar.

We notice that in this case as well, GOFA was successfull in updating the attack vectors in order to generate new attacks bypassing the filter. However, in this case the GOFA algorithm generated as many as 61 states of the filter in the DFA case and 31 states in the SFA case until a succesfull attack vector was detected. Against we notice that the speedup of using the SFA algorithm is huge.

To conclude with the evaluation of the GOFA algorithm, although as we already discussed in section VI, the GOFA algorithm is necessarily either incomplete or inefficient in the worst case, it performs well in practice detecting both vulnerabilities when they exist and inferring a large part of the targeted filter when it is not able to detect a vulnerability.

### E. Cross Checking HTML Encoder implementations

To demonstrate the wide applicability of our sanitizer inference algorithms we reconsider the experiment performed in the original BEK paper [8]. The authors, payed a number of freelancer developers to develop HTML encoders. Then they took these HTML encoders, along with some other existing implementations and manually converted them to BEK programs. Then, using BEK the authors were able to find differences in the sanitizers and check properties such as idempotence.

Using our learning algorithms we are able to perform a similar experiment but this time completely automated and in fact, without any access to source code of the implementation. For our experiments we used 3 different encoders from the PHP language, the HTML encoder from the .net AntiXSS library [30] and then, we also inferred models for the HTML encoders used by Twitter, Facebook and Microsoft Outlook email service.

We used our transducer learning algorithms in order to infer models for each of the sanitizers which we then converted to BEK programs and checked for equivalence and idempotence using the BEK infrastructure. A function \( f \) is idempotent if \( \forall x, f(f(x)) = f(x) \) or in other words, reapplying the sanitizer to a string which was already sanitized won’t change the resulting string. This is a nice property for sanitizers because it means that we easily reapply sanitization without worrying about breaking the correct semantics of the input string.

In our algorithm, we used a simple form of symbolic transducer learning, as sketched in section V-C, where we gen-
that we tested. Will skip encoding the semicolon, as did every other sanitizer encode unicode characters in their decimal representations but On the other hand, the .net AntiXSS implementation will HTML entities in their decimal representations. For example, the older encoder of the AntiXSS library which was encoding all service. The encoder in the outlook email seems to match an function did not match the one in the MS Outlook email to detect whether the current character is part of an already encoded HTML entity. idempotent requires a large amount of lookahead symbols to point out that although in general html encoders can be not to reencode already encoded html entities. We would like htmlspecialcharacters < to avoid confusion with the "" symbol. The idempotent func-
tion did not match the one in the MS Outlook email although [36] implements a symbolic version of Angluin’s algorithm, in their system the predicates are obtained through symbolic execution in combination with the Shabaz-Groz state transducers was extended in a follow up paper [15]. Hooimeijer et al. [8] and the theory behind symbolic finite automata [11], although similar constructions were suggested much earlier [31]. The BEK language was introduced by Hooimeijer et al. [8] and the theory behind symbolic finite state transducers was extended in a follow up paper [15]. Symbolic automata, transducers and the BEK language is a very active area of research [14], [32]–[35] and we expect that BEK programs will get more widespread adoption in the near future. In the inference of symbolic automata and transducers there are two relevant recent works. Botincan and Babic [36] used symbolic execution in combination with the Shabaz-Groz algorithm in order to infer symbolic models of programs as symbolic lookback transducers. Although the authors claim that equivalence of symbolic lookback transducers(SLT) is decidable a paper published recently by Veanes [37] shows that equivalence of SLTs is in fact undecidable. Moreover, although [36] implements a symbolic version of Angluin’s algorithm, in their system the predicates are obtained through
eralized the most commonly seen output term to all alphabet members not explicitly checked.

As an alphabet, we used a subset of characters including standard characters that should be encoded under the HTML standard and moreover, a set of other characters, including unicode characters, to provide completeness against different implementations. For the simulation of the equivalence oracle we produced random strings from a predefined grammar including all the characters of the alphabet and in addition many encoded HTML character sequences. The last part is important for detecting if the encoder is idempotent.

Figure 8 shows the results of our experiment. We found that most sanitizers are different and only one sanitizer is idempotent. All the entries of the figure represent the character or string that the two sanitizers are different or a tick if they are equal. One exception is the entries labelled with u8249 which denotes the unicode character with decimal representation \u8249; We included the decimal representation in the table to avoid confusion with the “<” symbol. The idempotent sanitizer is a version of htmlspecialcharacters function with a special flag disabled, that instructs the function not to reencode already encoded html entities. We would like to point out that although in general html encoders can be represented by single state transducers, making the encoder idempotent requires a large amount of lookahead symbols to detect whether the current character is part of an already encoded HTML entity.

Another surprising result is that the .net HTML encoding function did not match the one in the MS Outlook email service. The encoder in the outlook email seems to match an older encoder of the AntiXSS library which was encoding all HTML entities in their decimal representations. For example, this encoder is the only one encoding the semicolon symbol. On the other hand the .net AntiXSS implementation will encode unicode characters in their decimal representations but will skip encoding the semicolon, as did every other sanitizer that we tested.

At this point, we would like to stress that our results are not conclusive. For example, the fact that we found that the twitter and facebook encoders are equal does not mean that there is no string in which the two sanitizers differ. This is a fundamental limitation of all black-box testing algorithms. In fact, even the results on differences between sanitizers might be incorrect in principle. However, in this case we can easily verify the differences and, if necessary, update the corresponding models for the encoders.

VIII. RELATED WORK

Our work is mainly motivated by recent advances in the analysis of sanitizers and regular expressions, a line of work which was initiated with the introduction of symbolic automata [11], although similar constructions were suggested much earlier [31]. The BEK language was introduced by Hooimeijer et al. [8] and the theory behind symbolic finite state transducers was extended in a follow up paper [15].
symbolic execution, and therefore, there is no need to infer the predicate guards or infer the correct transitions for each state. Since their system is using the Shabaz-Groz algorithm, our improved counterexample processing would provide an exponentially faster way to handle counterexamples in their case too.

The second closely related work in the inference of symbolic automata was done by Maller and Mens [22]. They describe an algorithm to infer automata over ordered alphabets which is a specific instantiation of symbolic automata. However, in order to correctly infer such an automaton the authors assume that the counterexample given by the equivalence oracle is of minimal length and this assumption is used in order to distinguish between a wrong transition in the hypothesis or a hidden state. Unfortunately, verifying that a counterexample is minimal requires an exponential number of queries and thus this assumption does not lead to a practical algorithm for inferring symbolic automata. On the other hand, our algorithm is more general, as it works for any kind of predicate guards as long as they are learnable, and moreover does not assume a minimal length counterexample making the algorithm practical.

The work on active learning of DFAs was initiated by Angluin [19] after a negative result of Gold [38] who showed that it is NP-Hard to infer the minimal automaton consistent with a set of samples. After its introduction, Angluin’s algorithm was improved and many variations were introduced; Rivest and Schapire [20] showed how to improve the query complexity of the algorithm and introduced the binary search method for processing counterexamples. Balcazar et al. [39] describe a general approach to view the different variations of Angluin’s algorithm.

Shabaz and Groz [12] extended Angluin’s algorithm to handle Mealy Machines and introduced the counterexample processing we discussed above. Their approach was then extended by Khalili and Tacchella [40] to handle non deterministic Mealy Machines. However, as we point out above mealy machines in general are not expressive enough to model complex sanitization functions. Moreover, the algorithm by Khalili and Tacchella uses the Shabaz-Groz counterexample processing thus it can be improved using our method. Since Shabaz-Groz is used in many contexts including the reverse engineering of Command and Control servers of botnets [41], we believe that our improved counterexample processing method will find many applications. Lately, inference techniques were developed for more complex classes of automata such as register automata [42]. These automata are allowed to use a finite number of registers [43]. Since registers are also used in some case during the analysis of sanitizer functions [15], and specifically decoders, we believe that expanding our work to handle register versions of symbolic automata and transducers is a very interesting direction for future work.

The implementation of our equivalence oracle is inspired by the work of Peled et al. [23]. In their work, a similar equivalence oracle implementation is described for checking Buichi automata, however, their implementation also utilizes the Vasilleski-Chow algorithm [44], an algorithm for checking compliance of two automata, given an upper bound on the size of the black-box automaton. This algorithm however, has a worst case exponential complexity a fact which makes it impractical for real applications. On the other hand, we demonstrate that our GOFA algorithm is able to infer 90% of the states of the target filter on average.

The algorithm for initializing the observation table was first described by Groce et al. [45]. In their paper they describe the initialization procedure and prove two lemmas regarding the efficiency of the procedure in the context of their model checking algorithm. However, the lemma proved just shows convergence and they are not concerned with the reduction of equivalence queries as we prove.

There is a large body of work regarding whitebox program analysis techniques that aim at validating the security of sanitizer code. The SANER [4] project uses static and dynamic analysis to create finite state transducers which are overapproximations of the sanitizer functions of programs. Minamide [5] constructs a string analyzer for PHP which is used to detect vulnerabilities such as cross site scripting. He also describes a classification of various PHP functions according to the automaton model needed to describe them. The Reggae system [6] attempts to generate high coverage test cases with symbolic execution for systems that use complex regular expressions. Wasserman and Su [7] utilize Context free grammars to construct overapproximations of the output of a web application. Their approach could be used in order to implement a grammar which can then be used as an equivalence oracle when applying the cross checking algorithm for verifying equality between two different implementations.

IX. CONCLUSIONS AND FUTURE WORK

Clearly, we are light of need for robust and complete blackbox analysis algorithms for filter programs. In this paper we presented a first set of algorithms which could be utilized to analyze such programs. However, the space for research in this area is still vast. We believe that our algorithms can be further tuned in order to achieve an even larger performance increase. Moreover, more complex automata model which are currently being used [14], [43] can be also utilized to further reduce the number of queries required to infer a sanitizer model. Finally, we point out that totally different models might be necessary to handle other types of filters programs which are based on big data analytics or on the analysis of network protocols. Thus, to conclude we believe that black-box analysis of filters and sanitizers presents a fruitful research area which deserves more attention due to both scientific interest and practical applications.

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REFERENCES


APPENDIX

A. Comparison of GOFA algorithm with random testing

Regarding the usefulness of GOFA algorithm as a security auditing method it is important to consider it in comparison to random testing/fuzzing. Currently, most tools in the black-box testing domain, such as web vulnerability scanners, work
by fuzzing the target filter with various attack strings until a bypass is found or the set of attack strings is exhausted.

We argue that our GOFA algorithm is superior to fuzzing for two reasons:

1) The number of queries of the GOFA algorithm is independent of the size of the grammar. On the other hand, when producing random strings from a grammar in order to test a filter a very large number of strings has to be produced. Moreover, testing for modern vulnerabilities such as XSS is very complex, since there is a large number of variations that one should consider (cf. [46]).

2) Random testing produces no information on the structure of the filter if no attack is found. Consider the case where one produces a large number of candidate attack strings, but no bypass is found. Then, the auditor is left with no additional information for the filter, other than it rejected the set of strings that was tested. One approach would be to try to infer the structure of an automaton from that set of strings. Unfortunately, inferring the minimal automaton which is consistent with a set of strings is NP-Hard to approximate even within any polynomial factor [47]. On the other hand, as we demonstrate our GOFA algorithm is able to recover on average 90% of the states of the target filter in cases where no attack exists and an expressive enough grammar is given as input.

B. Approximating a Complete Equivalence Oracle

Although the GOFA algorithm is a suitable equivalence oracle implementation in the case the goal is to audit a target filter, in some cases one would like to recover a complete model of the target filter/sanitizer. In such cases, finding a bypass is not enough. Since we only assume black-box access to the target filter, in order for this problem to be even solvable we have to assume an upper bound on the size of the target filter. In this case, The Vasilevskii-Chow(VC) algorithm [44] exists for checking compliance between a DFA and a target automaton given black-box access to the second.

However, if the DFA at hand has $n$ states and the upper bound given is $m$ then the VC algorithm is exponential in $m - n$. Moreover, the algorithm suffers from the same limitations in the alphabet size as DFA learning algorithms since every possible transition of the black-box automaton must be checked. Creating a symbolic version of the VC algorithm may be possible however, we will again only get probabilistic guarantees on the correctness of our equivalence oracle.

Another option is to construct a context free grammar describing the input protocol under which the sanitizer should operate and then use random sampling from that grammar to test whether the hypothesis and the target programs are complying. For example, when we test HTML Encoders we might want to construct a grammar with a number of different character sequences such as encoded HTML entities or special characters and test the behavior of the encoder under these strings. We employ this approach in our experiments. Finally, static analysis techniques [7] can be used to generate a CFG describing the output of another implementation of the same sanitizer or filter and then cross check the generated CFG with the target sanitizer using our fingerprint algorithm.

C. Converting Transducers to BEK Programs

In this section we will describe our algorithm to convert finite state transducers into BEK programs. The assumptions we have is that the transducers given to our algorithm are single-valued transducers with bounded lookahead and domain $\Sigma^*$. Due to lack of space, we won't describe here the full specification of the BEK language. We urge the interested reader to refer to the original BEK paper [8] as well as to the online tutorial [48].

Figure 9 presents the general template of a BEK program. In a nutshell the BEK language allows one to define an iterator over the input string. In addition, a predefined number of registers taking integer values can be used. Inside the iterator loop an outer switch-case statement is placed, with guards defined by the programmer. Inside each case loop the programmer is allowed to place an if-then-else statement with an arbitrary number of else-if statements and a final else statement. In order to produce an output symbol the yield statement is used, which can also produce multiple output symbols. After the main iteration over the input is over, a BEK program can have a final series of case statements which will be evaluated over the register variables defined on the program after exiting the input iteration. We call these statements the end part of the iterator.

The overall construction is straightforward in the case the transducer is deterministic: We define a register $s$ which at each point of the computation holds the current state of the transducer. The outer case loop of the program checks the state number while, an internal if-then-else chain matches the current input character and afterwards, sets the next state and yields the corresponding symbol of the transition, if any.

Unfortunately, when a bounded lookahead is present a more complicated situation arises, because the BEK language cannot process more than one input characters at each iteration. Thus, the program needs to manually store a buffer and keep track of all the alternative states the transducer might be in until a lookahead is matched or discarded.

In fact, as we demonstrate in appendix E, this complexity can easily lead to errors in BEK programs. Indeed, we found a problem in an HTML decoder program which was given as an example in the BEK tutorial. The problem occurred because the BEK program was not taking into account all possibilities when a lookahead string was partially matched and then discarded.

The overall structure of a BEK program with lookahead transitions is similar with the basic structure. However, we add
additional guards in all states that can be part of a lookahead transition as follows:

Consider each path starting in a final state \( q_{\text{src}} \) and ending in a final state \( q_{\text{dst}} \) through a path of non-final states, while consuming an input string \( r \), \( |r| = k \) and generating an output \( o \). In other words, this path is a lookahead transition which consumes the input string \( r \) and produces the string \( o \). Then we perform the following:

1) For each prefix of \( r \), \( r_i \) for all \( i < k \) compute the set of states \( S_i \) which are accessible from state \( q_{\text{src}} \) with the string \( r_i \). Since the transducer is single-valued this set contains exactly one final state. The set \( S_i \) of accessible states can be easily computed using a BFS search. Moreover, let \( o_i \) be the output of the transducer on string \( r_i \) from state \( q_{\text{src}} \). We save for each prefix \( i \) the triple \( (r_i, o_i, S_i) \).

2) Let \( s_i \) be the non-final state reached by \( r_i \) if the suffix following \( r_i \) is the remaining symbols of \( r \). Then, for every state \( s \in S_i \) add inside the case statement containing the guards of \( s_i \) the guards of each \( s \in S \) ordered in a way such that the unique final state in \( S_i \) is checked last.

3) In the end part of the iterator, add for each prefix \( i \) a case guard asserting that if the computation ended in state \( s_i \) then the program must yield the string \( o_i \). These statements handle the case where the input is finished while processing a lookahead transition.

As soon as we add these additional guards for every lookahead transition the BEK program is completed.

D. Decision trees as SFA

Although are main focus in developing a learning algorithm for SFAs lies in the inference of regular expression filters, SFAs is a very general computation model which allow us to represent various data structures. In figure 10 we show the representation of a decision tree over the real numbers, as a SFA. The predicate family here is the set of linear inequalities of one variable over the real numbers. If we restrict the alphabet \( \Sigma \) to an, infinite, subset of the real numbers such that \( \max_{w \in \Sigma} |w| = R \) and moreover, there is a margin \( \gamma \) for every predicate guard \(^3\), then, predicate guards of size \( k \) will be \( O(kR^2/\gamma^2) \)-learnable \([49]\) and thus the overall decision tree can be efficiently inferred using our algorithm.

E. Bug in BEK HTML Decoder Example

While developing and debugging our implementation we found a bug in an example implementation of a simplified HTML decoder in the online BEK tutorial. The program in question is the program named \texttt{decode} from the second part of the BEK tutorial \([48]\). We won’t present the whole program here due to space constraints, but the problem occurs in the following case:

```java
    case (s == 1) :                        //memorized &
      if (c == '\&') { yield ('&'); }
      else if (c == 'l') { s := 2; }
```

\(^3\)A margin \( \gamma \) for a linear inequality \( \sum_i a_i \chi_i \geq \theta \) means that, for all \( \chi \in \Sigma |\sum_i a_i \chi_i + \theta| > \gamma \)

We believe that this bug demonstrates the complexity of writing sanitizers that make heavy use of lookahead transitions in BEK. One should implement a large number of nested if-then-else statements, like we describe in our conversion algorithm in section VII-E. We believe that the BEK language could become much simpler with the introduction of a string compare function to allow the programmers to easily handle lookaheads. This may require extra work on the backend of the BEK compiler, however we believe that this is a feasible task, that will greatly simplify the language.

F. Proofs of Theorems and Lemmas

Proof: (of Theorem 1) We need to show that the algorithm does progress towards the discovery of a correct hypothesis. Recall that the algorithm starts with an \( SOT \) that is closed and reduced. Each time the algorithm has an \( SOT \) that satisfies these properties an equivalence query is issued resulting either in termination or in a counterexample. Processing the counterexample will require \( O(\log m + n) \) membership queries. The counterexample will either make the \( SOT \) not closed (in which case a new state is introduced) or it will lead to the introduction of an element \( s_{\text{tr}} \) in \( \Lambda \). A pair of access
strings \((s, s')\) will be called completed if it holds that the guard predicate \(\phi\) in the transition \((s, \phi, s')\) of the hypothesis is logically equivalent to the predicate \(\phi\) that is in the transition between states \(q_s\) and \(q_{s'}\) in the target SFA. We will show that for the new element \(s_{i0}\) that is added in \(\Lambda\) it holds that it corresponds to an \(s'\) for which \((s_{i0}, s')\) is not yet completed. For the sake of contradiction suppose the opposite is true, i.e., that \(s_{i0}, b \equiv s' \mod W \cup \{d\}\) for some \(s'\) for which \((s, s')\) is completed. It follows that the transition \((q_{s_{i0}}, \phi, q_{s'})\) found in the Hypothesis SFA is correct and it will hold that \(\phi(b)\) and also \(s_{i0}, b \equiv s' \mod W \cup \{d\}\). In turn this means that \(s_{i0}, b \equiv s' \mod W\) and as a result \(s_{i0+1} \equiv s' \mod W\). Because the hypothesis SFA is reduced we obtain \(s' = s_{i0+1}\) which is a contradiction since \(s_{i0}, b \not\equiv s_{i0+1} \mod W \cup \{d\}\). It follows that \(s_{i0}, b \equiv s_j \mod W \cup \{d\}\) for some \(j, j \not= i0 + 1\) and the pair \((s_{i0}, s_j)\) is not yet completed. We conclude that \((b, s_j)\) is a counterexample w.r.t. \((R, \phi, s)\) where \(R\) is the input to the guard\(\) algorithm for the construction of the guard of state \(s_{i0}\) in the hypothesis and \(\phi\) is the guard predicate of the state \(q_{s_{i0}}\) in the target automaton. Indeed, \((\phi, s_{i0+1})\) is in the output of guard\(\)() and it holds that \(\phi(b) = 1\), while \(\phi_{i0+1}(b) = 0\) as \(j \not= i0 + 1\) and \(\phi_{j}(b) = 1\). Using the above, the equivalence queries that result in closed SOT tables cannot exceed \(nt(k)\).

On the other hand, if an equivalence query results in an SOT that is not closed this results in the introduction of a new state; no membership queries will be needed in this case as the row \(s_{i0}, b\) is already determined with respect to \(W \cup \{d\}\).

The statement of the theorem follows.

Proof: (of Theorem 2) First of all observe that there is at least one index \(j^* \in \{0, \ldots, |z'| - 1\}\) with the property that \(\gamma_j^* \not= \gamma_{j^*+1}\). Indeed if the negation of this statement holds it will contradict with the statement that \(\gamma_0 \not= \gamma_{|z'|}\). Let \(J^*\) be the set of all such indices. The proof of the theorem is by induction using the previous observation as basis. Suppose that the given range \([j_{\text{left}}, j_{\text{right}}]\) satisfies the property that it intersects with \(J^*\). We will prove that the next range selected by the binary search process as described above preserves the property and it also intersects with \(J^*\). Suppose that \(j\) is the middle point of \([j_{\text{left}}, j_{\text{right}}]\) and \(\gamma_j = \gamma_0\). The search process selects \([j, j_{\text{right}}]\) as the next range. Suppose for the sake of contradiction that \([j, j_{\text{right}}]\) has no intersection with \(J^*\); this implies \(\gamma_{j_{\text{right}}} = \gamma_0\). In case \(j_{\text{right}} = |z'|\) this leads immediately to a contradiction. On the other hand, if \(j_{\text{right}} < |z'|\) this means that at a previous stage \(j_{\text{right}} + 1\) was a middle point and the binary search process decided to choose the left sub-range. By definition this implies that \(\gamma_{j_{\text{right}}+1} \not= \gamma_0\). As a result, since \(\gamma_{j_{\text{left}}} = \gamma_0\) we obtain that \(j_{\text{right}} \in J^*\) which is again a contradiction. For the second case, suppose that \(\gamma_j \not= \gamma_0\) and thus the search process selects \([j_{\text{left}}, j - 1]\) as the next range. Suppose, for the sake of contradiction that \([j_{\text{left}}, j - 1]\) has no intersection with \(J^*\). In case \(j_{\text{left}} = 0\) then \(\gamma_{j-1} = \gamma_0\) and since \(\gamma_j \not= \gamma_0\) we have that \(j - 1 \in J^*\) hence a contradiction. On the other hand, if \(j_{\text{left}} > 0\) this means that at a previous stage of the binary search process, \(j_{\text{left}}\) was a middle point and a decision to go right was made. In turn this implies that \(\gamma_{j_{\text{left}}} = \gamma_0\). However by assumption \(\gamma_j \not= \gamma_0\) and thus there must be an index in \([j_{\text{left}}, j - 1]\) that belongs to \(J^*\), a contradiction.

Proof: (Sketch) (of Theorem 3) The algorithm starts with the empty string as the sole access string and attempts to close the observation table by issuing transduction queries. Eventually the table will become closed, possibly with the addition of certain lookahead transitions in the list \(L\) with the respective columns in the observation table. Now it is easy to notice that the SG counterexample processing method will add a distinguishing suffix if the counterexample is due to a hidden state while the prefix-closed queries will detect and process any undiscovered lookahead transition, thus the algorithm will eventually terminate with a correct hypothesis.

Regarding the complexity of the algorithm, notice that the algorithm will issue a prefix-closed query only in order to fill certain entries in the observation table. Therefore, it suffices to bound the size of the rows and columns of the table. The rows of the table remain the same as in the Shabaz-Groz algorithm and therefore, we have at most \((|\Sigma| + 1)n\) rows. The table is initialized with \(|\Sigma|\) columns corresponding to each symbol of the alphabet. A column is added either when we process a counterexample due to a hidden state or an undiscovered lookahead transition. We distinguish between the two cases:

- In case the counterexample is due to a hidden state, then at most \(m\) columns are added. Since there are at most \(n\) counterexamples due to hidden states the total number of columns added can be at most \(mn\).
- In case the counterexample is due to an undiscovered lookahead transition, we notice that the length of the path can be at most \(n\), since we have a bounded lookahead, and therefore at most \(n\) columns will be added. Thus, since there is a total of \(k\) lookahead transitions at most \(kn\) columns will be added.

We notice that each prefix-closed membership query can be implemented with at most \(\max\{n, m\}\) membership queries, since the longest column is of length \(\max\{n, m\}\) and the longest row is of length \(n\). Finally, since a counterexample will be either due to a hidden state or an undiscovered lookahead transition it follows that we can have at most \(n + k\) equivalence queries.