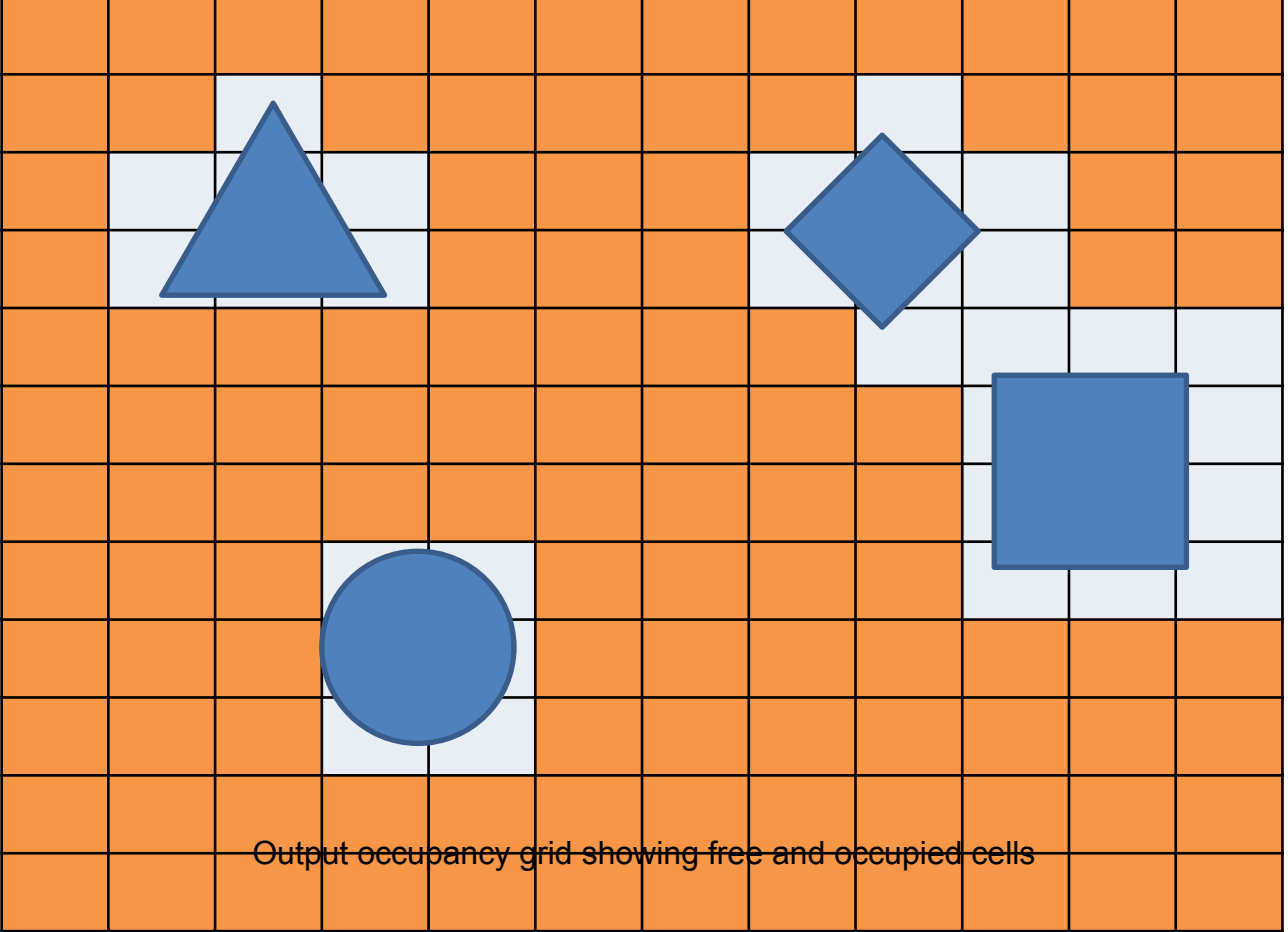


Environment Before mapping



Output occupancy grid showing free and occupied cells